

# Physics/Engineering Equation Sheet

## 1 Fluid Dynamics Conservation Equations

### 1.1 Integral Form

**Mass:**

$$\frac{\partial}{\partial t} \iiint \rho dV + \iint \rho \mathbf{u} \cdot d\mathbf{S} = 0$$

**Momentum:**

$$\begin{aligned} \frac{\partial}{\partial t} \iiint \rho \mathbf{u} dV + \iint \rho (\mathbf{u} \cdot d\mathbf{S}) \mathbf{u} \\ = \iiint \rho \mathbf{F} dV - \iint p d\mathbf{S} + \mathbf{F}_{viscous} \end{aligned}$$

**Energy:**

$$\begin{aligned} \frac{\partial}{\partial t} \iiint \rho (e + \frac{1}{2} \mathbf{u} \cdot \mathbf{u}) dV + \iint \rho (e + \frac{1}{2} \mathbf{u} \cdot \mathbf{u}) \mathbf{u} \cdot d\mathbf{S} \\ = \iiint \dot{q} \rho dV + \dot{Q}_{viscous} - \iint p \mathbf{u} \cdot d\mathbf{S} \\ + \iiint \rho (\mathbf{f} \cdot \mathbf{u}) dV + \dot{W}_{viscous} \end{aligned}$$

### 1.2 Differential Form

**Mass:**

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0$$

**Momentum:**

$$\begin{aligned} \rho \left( \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) &= \rho \mathbf{F} - \nabla p + \nabla \cdot \boldsymbol{\tau} \\ &= \rho \mathbf{F} - \nabla p + \mu \nabla^2 \mathbf{u} + \frac{1}{3} \mu \nabla (\nabla \cdot \mathbf{u}) \\ &\quad + \kappa \nabla (\nabla \cdot \mathbf{u}) + 2(\nabla \mu) \cdot \nabla \mathbf{u} + (\nabla \mu) \times (\nabla \times \mathbf{u}) \\ &\quad - \frac{2}{3} (\nabla \mu) (\nabla \cdot \mathbf{u}) + (\nabla \kappa) (\nabla \cdot \mathbf{u}) \\ \kappa &= \lambda + \frac{2}{3} \mu \quad (\text{bulk viscosity}) \end{aligned}$$

$$\boldsymbol{\tau} = \mu [\nabla \mathbf{u} + (\nabla \mathbf{u})^\top] + (\kappa - \frac{2}{3} \mu) (\nabla \cdot \mathbf{u}) \mathbf{I}$$

$$\mathbf{I} = \sum_{i=1}^3 \sum_{j=1}^3 \delta_{ij}$$

**Vorticity:**

$$\begin{aligned} \frac{\partial \boldsymbol{\Omega}}{\partial t} + \nabla \times (\boldsymbol{\Omega} \times \mathbf{u}) &= \nabla \times \mathbf{F} + \frac{\nabla \rho \times \nabla p}{\rho^2} \\ &\quad + \nu \nabla^2 \boldsymbol{\Omega} + (\nabla \nu) \times \left[ \frac{3}{2} \nabla (\nabla \cdot \mathbf{u}) - \nabla^2 \boldsymbol{\Omega} \right] \end{aligned}$$

$$\begin{aligned} \nabla \times (\boldsymbol{\Omega} \times \mathbf{u}) &= \boldsymbol{\Omega} (\nabla \cdot \mathbf{u}) + (\mathbf{u} \cdot \nabla) \boldsymbol{\Omega} - (\boldsymbol{\Omega} \cdot \nabla) \mathbf{u} \\ \boldsymbol{\Omega} &= \nabla \times \mathbf{u} \quad \text{and} \quad \nu = \mu/\rho \end{aligned}$$

**Energy:**

$$\begin{aligned} \frac{\partial (\rho e_t)}{\partial t} &= -\nabla \cdot [(p + \rho e_t) - \boldsymbol{\tau} \cdot \mathbf{u} + \mathbf{q}] \quad (\text{total energy}) \\ \rho \frac{De}{Dt} &= -\nabla \cdot \mathbf{q} - p \nabla \cdot \mathbf{u} + \boldsymbol{\tau} : \nabla \mathbf{u} \quad (\text{internal energy}) \\ \rho \frac{Dh}{Dt} &= -\nabla \cdot \mathbf{q} + \frac{Dp}{Dt} + \boldsymbol{\tau} : \nabla \mathbf{u} \quad (\text{specific enthalpy}) \\ \rho c_p \frac{DT}{Dt} &= -\nabla \cdot \mathbf{q} + \beta T \frac{Dp}{Dt} + \boldsymbol{\tau} : \nabla \mathbf{u} \quad (\text{temperature}) \\ \rho \frac{Ds}{Dt} &= -\nabla \cdot \left( \frac{\mathbf{q}}{T} \right) - \frac{\mathbf{q}}{T^2} \cdot \nabla T + \frac{\boldsymbol{\tau} : \nabla \mathbf{u}}{T} \quad (\text{specific entropy}) \\ \rho c_p \frac{DT}{Dt} &= \nabla (\lambda \nabla T) + \beta T \frac{Dp}{Dt} + \boldsymbol{\tau} : \nabla \mathbf{u} \quad (\text{Fourier conduction}) \end{aligned}$$

$$\begin{aligned} \boldsymbol{\tau} : \nabla \mathbf{u} &= \mu \left\{ 2(\nabla \mathbf{u})_{11}^2 + 2(\nabla \mathbf{u})_{22}^2 + 2(\nabla \mathbf{u})_{33}^2 \right. \\ &\quad \left. + [(\nabla \mathbf{u})_{12} + (\nabla \mathbf{u})_{21}]^2 \right. \\ &\quad \left. + [(\nabla \mathbf{u})_{13} + (\nabla \mathbf{u})_{31}]^2 \right. \\ &\quad \left. + [(\nabla \mathbf{u})_{23} + (\nabla \mathbf{u})_{32}]^2 \right\} \\ &\quad + \left( \kappa - \frac{2}{3} \mu \right) (\nabla \cdot \mathbf{u})^2 \end{aligned}$$

**Thermodynamic Relations:**

$$e_t = e + \frac{1}{2} \mathbf{u} \cdot \mathbf{u} + \psi \quad (\text{total energy})$$

**Constant Specific Heat:**

$$\hat{u} = \int c_v dT \approx c_v T + \text{const}$$

## 2 Vector Identities

### 2.1 Algebraic Identities

$$\begin{aligned}\sin \theta &= \frac{\|\mathbf{A} \times \mathbf{B}\|}{\|\mathbf{A}\| \|\mathbf{B}\|} \\ \cos \theta &= \frac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{A}\| \|\mathbf{B}\|} \\ \|\mathbf{A} \times \mathbf{B}\|^2 + (\mathbf{A} \cdot \mathbf{B})^2 &= \|\mathbf{A}\|^2 \|\mathbf{B}\|^2 \\ \mathbf{A} + \mathbf{B} &= \mathbf{B} + \mathbf{A} \\ \mathbf{A} \cdot \mathbf{B} &= \mathbf{B} \cdot \mathbf{A} \\ \mathbf{A} \times \mathbf{B} &= -\mathbf{B} \times \mathbf{A} \\ &= \mathbf{e}_1 (A_2 B_3 - A_3 B_2) + \mathbf{e}_2 (A_3 B_1 - A_1 B_3) + \mathbf{e}_3 (A_1 B_2 - A_2 B_1) \\ c(\mathbf{A} + \mathbf{B}) &= c\mathbf{A} + c\mathbf{B} \\ (\mathbf{A} + \mathbf{B}) \cdot \mathbf{C} &= \mathbf{A} \cdot \mathbf{C} + \mathbf{B} \cdot \mathbf{C} \\ (\mathbf{A} + \mathbf{B}) \times \mathbf{C} &= \mathbf{A} \times \mathbf{C} + \mathbf{B} \times \mathbf{C} \\ \mathbf{A} \cdot (\mathbf{B} \times \mathbf{C}) &= \mathbf{B} \cdot (\mathbf{C} \times \mathbf{A}) = \mathbf{C} \cdot (\mathbf{A} \times \mathbf{B}) \\ \mathbf{A} \times (\mathbf{B} \times \mathbf{C}) &= (\mathbf{A} \cdot \mathbf{C}) \mathbf{B} - (\mathbf{A} \cdot \mathbf{B}) \mathbf{C} \\ \mathbf{A} \times (\mathbf{B} \times \mathbf{C}) + \mathbf{C} \times (\mathbf{A} \times \mathbf{B}) + \mathbf{B} \times (\mathbf{C} \times \mathbf{A}) &= 0 \\ (\mathbf{A} \times \mathbf{B}) \cdot (\mathbf{C} \times \mathbf{D}) &= (\mathbf{A} \cdot \mathbf{C})(\mathbf{B} \cdot \mathbf{D}) - (\mathbf{B} \cdot \mathbf{C})(\mathbf{A} \cdot \mathbf{D}) \\ |\mathbf{A} \times \mathbf{B}|^2 &= (\mathbf{A} \cdot \mathbf{A})(\mathbf{B} \cdot \mathbf{B}) - (\mathbf{A} \cdot \mathbf{B})^2\end{aligned}$$

### 2.2 Differentiation of vectors

$$\begin{aligned}\frac{d\mathbf{A}}{dt} &= \frac{dA_1}{dt} \mathbf{i} + \frac{dA_2}{dt} \mathbf{j} + \frac{dA_3}{dt} \mathbf{k} \\ \frac{d}{dt}(\mathbf{A} + \mathbf{B}) &= \frac{d\mathbf{A}}{dt} + \frac{d\mathbf{B}}{dt} \\ \frac{d}{dt}(\phi \mathbf{A}) &= \frac{d\phi}{dt} \mathbf{A} + \phi \frac{d\mathbf{A}}{dt} \\ \frac{d}{dt}(\mathbf{A} \cdot \mathbf{B}) &= \frac{d\mathbf{A}}{dt} \cdot \mathbf{B} + \mathbf{A} \cdot \frac{d\mathbf{B}}{dt} \\ \frac{d}{dt}(\mathbf{A} \times \mathbf{B}) &= \frac{d\mathbf{A}}{dt} \times \mathbf{B} + \mathbf{A} \times \frac{d\mathbf{B}}{dt} \\ \frac{d}{dt}(\mathbf{A} \times \mathbf{B} \cdot \mathbf{C}) &= \frac{d\mathbf{A}}{dt} \times \mathbf{B} \cdot \mathbf{C} + \mathbf{A} \times \frac{d\mathbf{B}}{dt} \cdot \mathbf{C} + \mathbf{A} \times \mathbf{B} \cdot \frac{d\mathbf{C}}{dt}\end{aligned}$$

### 2.3 First Derivative Identities

#### 2.3.1 Distributive Properties

$$\begin{aligned}\nabla(\psi + \phi) &= \nabla\psi + \nabla\phi \\ \nabla(\mathbf{A} + \mathbf{B}) &= \nabla\mathbf{A} + \nabla\mathbf{B} \\ \nabla \cdot (\mathbf{A} + \mathbf{B}) &= \nabla \cdot \mathbf{A} + \nabla \cdot \mathbf{B} \\ \nabla \times (\mathbf{A} + \mathbf{B}) &= \nabla \times \mathbf{A} + \nabla \times \mathbf{B}\end{aligned}$$

#### 2.3.2 Product rule for multiplication by a Scalar

$$\begin{aligned}\nabla(\psi\phi) &= \phi\nabla\psi + \psi\nabla\phi \\ \nabla(\psi\mathbf{A}) &= (\nabla\psi)\mathbf{A}^\top + \psi\nabla\mathbf{A} = \nabla\psi \otimes \mathbf{A} + \psi\nabla\mathbf{A} \\ \nabla \cdot (\psi\mathbf{A}) &= \psi\nabla \cdot \mathbf{A} + (\nabla\psi) \cdot \mathbf{A} \\ \nabla \times (\psi\mathbf{A}) &= \psi\nabla \times \mathbf{A} + (\nabla\psi) \times \mathbf{A} \\ \nabla^2(fg) &= f\nabla^2g + 2\nabla f \cdot \nabla g + g\nabla^2f\end{aligned}$$

#### 2.3.3 Quotient rule for division by a scalar

$$\begin{aligned}\nabla\left(\frac{\psi}{\phi}\right) &= \frac{\phi\nabla\psi - \psi\nabla\phi}{\phi^2} \\ \nabla\left(\frac{\mathbf{A}}{\phi}\right) &= \frac{\phi\nabla\mathbf{A} - \nabla\phi \otimes \mathbf{A}}{\phi^2} \\ \nabla \cdot \left(\frac{\mathbf{A}}{\phi}\right) &= \frac{\phi\nabla \cdot \mathbf{A} - \nabla\phi \cdot \mathbf{A}}{\phi^2} \\ \nabla \times \left(\frac{\mathbf{A}}{\phi}\right) &= \frac{\phi\nabla \times \mathbf{A} - \nabla\phi \times \mathbf{A}}{\phi^2}\end{aligned}$$

#### 2.3.4 Dot Product Rule

$$\begin{aligned}\nabla(\mathbf{A} \cdot \mathbf{B}) &= (\mathbf{A} \cdot \nabla)\mathbf{B} + (\mathbf{B} \cdot \nabla)\mathbf{A} + \mathbf{A} \times (\nabla \times \mathbf{B}) + \mathbf{B} \times (\nabla \times \mathbf{A}) \\ \frac{1}{2}\nabla(\mathbf{A} \cdot \mathbf{A}) &= (\mathbf{A} \cdot \nabla)\mathbf{A} + \mathbf{A} \times (\nabla \times \mathbf{A})\end{aligned}$$

#### 2.3.5 Cross product rule

$$\begin{aligned}\nabla \cdot (\mathbf{A} \times \mathbf{B}) &= (\nabla \times \mathbf{A}) \cdot \mathbf{B} - \mathbf{A} \cdot (\nabla \times \mathbf{B}) \\ \nabla \times (\mathbf{A} \times \mathbf{B}) &= \mathbf{A}(\nabla \cdot \mathbf{B}) - \mathbf{B}(\nabla \cdot \mathbf{A}) + (\mathbf{B} \cdot \nabla)\mathbf{A} - (\mathbf{A} \cdot \nabla)\mathbf{B} \\ &= \nabla \cdot (\mathbf{B}\mathbf{A}^\top - \mathbf{A}\mathbf{B}^\top) \\ \mathbf{A} \times (\nabla \times \mathbf{B}) &= (\nabla\mathbf{B}) \cdot \mathbf{A} - (\mathbf{A} \cdot \nabla)\mathbf{B} \\ (\mathbf{A} \times \nabla) \times \mathbf{B} &= (\nabla\mathbf{B}) \cdot \mathbf{A} - \mathbf{A}(\nabla \cdot \mathbf{B}) \\ &= \mathbf{A} \times (\nabla \times \mathbf{B}) + (\mathbf{A} \cdot \nabla)\mathbf{B} - \mathbf{A}(\nabla \cdot \mathbf{B})\end{aligned}$$

### 2.4 Second Derivative Identities

$$\begin{aligned}\nabla \cdot (\nabla \times \mathbf{A}) &= 0 \\ \Delta\psi &= \nabla^2\psi = \nabla \cdot (\nabla\psi) \\ \nabla \cdot (\nabla \cdot \mathbf{A}) &\text{ is undefined} \\ \nabla \times (\nabla\phi) &= 0 \\ \nabla \times (\nabla \times \mathbf{A}) &= \nabla(\nabla \cdot \mathbf{A}) - \nabla^2\mathbf{A} \\ \nabla \times (\nabla \cdot \mathbf{A}) &\text{ is undefined}\end{aligned}$$

In the 2nd to last identity,  $\nabla^2$  is the vector Laplacian operating on the vector field  $\mathbf{A}$ .

### 2.5 Third Derivative Identities

$$\begin{aligned}\nabla^2(\nabla\psi) &= \nabla[\nabla \cdot (\nabla\psi)] = \nabla(\nabla^2\psi) \\ \nabla^2(\nabla \cdot \mathbf{A}) &= \nabla \cdot [\nabla(\nabla \cdot \mathbf{A})] = \nabla \cdot (\nabla^2\mathbf{A}) \\ \nabla^2(\nabla \times \mathbf{A}) &= -\nabla \times [\nabla \times (\nabla \times \mathbf{A})] = \nabla \times (\nabla^2\mathbf{A})\end{aligned}$$

### 3 Vector Differential Invariants

$$h_i = \sqrt{\sum_{k=1}^n \left( \frac{\partial x_k}{\partial q_i} \right)^2} \quad (\text{scale factors for orthogonal coordinate systems})$$

$$\nabla \psi \equiv \text{grad } \psi = \frac{\mathbf{i}_i}{h_i} \frac{\partial \psi}{\partial q_i}$$

$$\nabla \cdot \mathbf{u} \equiv \text{div } \mathbf{u} = \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial (u_1 h_2 h_3)}{\partial q_1} + \frac{\partial (u_2 h_3 h_1)}{\partial q_2} + \frac{\partial (u_3 h_1 h_2)}{\partial q_3} \right]$$

$$\nabla \times \mathbf{u} \equiv \text{curl } \mathbf{u} = \frac{\mathbf{i}_1}{h_2 h_3} \left[ \frac{\partial (u_3 h_3)}{\partial q_2} - \frac{\partial (u_2 h_2)}{\partial q_3} \right] + \dots$$

$$\nabla \cdot \nabla \psi = \nabla^2 \psi = \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial q_1} \left( \frac{h_2 h_3}{h_1} \frac{\partial \psi}{\partial q_1} \right) + \dots \right]$$

$$\nabla (\nabla \cdot \mathbf{u}) = \frac{\mathbf{i}_1}{h_1} \frac{\partial}{\partial q_1} \left\{ \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial (u_1 h_2 h_3)}{\partial q_1} + \frac{\partial (u_2 h_3 h_1)}{\partial q_2} + \frac{\partial (u_3 h_1 h_2)}{\partial q_3} \right] \right\} + \dots$$

$$\nabla \times (\nabla \times \mathbf{u}) = \frac{\mathbf{i}_1}{h_2 h_3} \left\langle \frac{\partial}{\partial q_2} \left\{ \frac{h_3}{h_1 h_2} \left[ \frac{\partial (u_2 h_2)}{\partial q_1} - \frac{\partial (u_1 h_1)}{\partial q_2} \right] \right\} - \frac{\partial}{\partial q_3} \left\{ \frac{h_2}{h_3 h_1} \left[ \frac{\partial (u_1 h_1)}{\partial q_3} - \frac{\partial (u_3 h_3)}{\partial q_1} \right] \right\} \right\rangle + \dots$$

$$\begin{aligned} \nabla^2 \mathbf{u} &= \mathbf{i}_1 \left[ \nabla^2 u_1 - u_1 h_1 \nabla^2 \frac{1}{h_1} \right. \\ &\quad + \frac{u_1 h_1}{h_1} \frac{\partial}{\partial q_1} (\nabla^2 q_1) + \frac{u_2 h_2}{h_1} \frac{\partial}{\partial q_1} (\nabla^2 q_2) + \frac{u_3 h_3}{h_1} \frac{\partial}{\partial q_1} (\nabla^2 q_3) \\ &\quad - \frac{2}{h_1^2} \frac{\partial (1/h_1)}{\partial q_1} \frac{\partial}{\partial q_1} (u_1 h_1) - \frac{2}{h_2^2} \frac{\partial (1/h_1)}{\partial q_2} \frac{\partial}{\partial q_1} (u_2 h_2) - \frac{2}{h_3^2} \frac{\partial (1/h_1)}{\partial q_3} \frac{\partial}{\partial q_1} (u_3 h_3) \\ &\quad \left. + \frac{1}{h_1} \frac{\partial (1/h_1^2)}{\partial q_1} \frac{\partial}{\partial q_1} (u_1 h_1) + \frac{1}{h_1} \frac{\partial (1/h_2^2)}{\partial q_1} \frac{\partial}{\partial q_2} (u_2 h_2) + \frac{1}{h_1} \frac{\partial (1/h_3^2)}{\partial q_1} \frac{\partial}{\partial q_3} (u_3 h_3) \right] + \dots \end{aligned}$$

$$\begin{aligned} \nabla \mathbf{u} &= \sum_{j=1}^3 \sum_{k=1}^3 \frac{\mathbf{i}_j}{h_j} \mathbf{i}_j \left( \mathbf{i}_k \frac{\partial u_k}{\partial q_j} + u_k \frac{\partial \mathbf{i}_k}{\partial q_j} \right); \quad \frac{\partial \mathbf{i}_k}{\partial q_j} = \frac{\mathbf{i}_j}{h_k} \frac{\partial h_j}{\partial q_k} \quad (j \neq k), \quad \frac{\partial \mathbf{i}_j}{\partial q_j} = -\frac{\mathbf{i}_k}{h_k} \frac{\partial h_j}{\partial q_k} - \frac{\mathbf{i}_l}{h_l} \frac{\partial h_j}{\partial q_l} \\ &= \frac{\mathbf{i}_1 \mathbf{i}_1}{h_1} \left[ \frac{\partial u_1}{\partial q_1} + \frac{u_2}{h_2} \frac{\partial h_1}{\partial q_2} + \frac{u_3}{h_3} \frac{\partial h_1}{\partial q_3} \right] + \frac{\mathbf{i}_1 \mathbf{i}_2}{h_1} \left[ \frac{\partial u_2}{\partial q_1} - \frac{u_1}{h_2} \frac{\partial h_1}{\partial q_2} \right] + \frac{\mathbf{i}_1 \mathbf{i}_3}{h_1} \left[ \frac{\partial u_3}{\partial q_1} - \frac{u_1}{h_3} \frac{\partial h_1}{\partial q_3} \right] \\ &\quad + \frac{\mathbf{i}_2 \mathbf{i}_1}{h_2} \left[ \frac{\partial u_1}{\partial q_2} - \frac{u_2}{h_1} \frac{\partial h_2}{\partial q_1} \right] + \frac{\mathbf{i}_2 \mathbf{i}_2}{h_2} \left[ \frac{\partial u_2}{\partial q_2} + \frac{u_3}{h_3} \frac{\partial h_2}{\partial q_3} + \frac{u_1}{h_1} \frac{\partial h_2}{\partial q_1} \right] + \frac{\mathbf{i}_2 \mathbf{i}_3}{h_2} \left[ \frac{\partial u_3}{\partial q_2} - \frac{u_2}{h_3} \frac{\partial h_2}{\partial q_3} \right] \\ &\quad + \frac{\mathbf{i}_3 \mathbf{i}_1}{h_3} \left[ \frac{\partial u_1}{\partial q_3} - \frac{u_3}{h_1} \frac{\partial h_3}{\partial q_1} \right] + \frac{\mathbf{i}_3 \mathbf{i}_2}{h_3} \left[ \frac{\partial u_2}{\partial q_3} - \frac{u_3}{h_2} \frac{\partial h_3}{\partial q_2} \right] + \frac{\mathbf{i}_3 \mathbf{i}_3}{h_3} \left[ \frac{\partial u_3}{\partial q_3} + \frac{u_1}{h_1} \frac{\partial h_3}{\partial q_1} + \frac{u_2}{h_2} \frac{\partial h_3}{\partial q_2} \right] \end{aligned}$$

$$\phi = \sum_{j=1}^3 \sum_{k=1}^3 \mathbf{i}_j \mathbf{i}_k \phi_{jk} \quad (\text{Dyadic})$$

$$\phi^\top = \sum_{j=1}^3 \sum_{k=1}^3 \mathbf{i}_j \mathbf{i}_k \phi_{kj} \quad (\text{Dyadic transpose})$$

## 4 Cylindrical/Spherical Vector Identities

### 4.1 Cylindrical

$$\begin{aligned}
\nabla\psi &= \mathbf{i}_r \frac{\partial\psi}{\partial r} + \mathbf{i}_\theta \frac{1}{r} \frac{\partial\psi}{\partial\theta} + \mathbf{i}_z \frac{\partial\psi}{\partial z} \\
\nabla^2\psi &= \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial\psi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2\psi}{\partial\theta^2} + \frac{\partial^2\psi}{\partial z^2} \\
\nabla \cdot \mathbf{u} &= \frac{1}{r} \frac{\partial}{\partial r} (ru_r) + \frac{1}{r} \frac{\partial u_\theta}{\partial\theta} + \frac{\partial u_z}{\partial z} \\
\nabla \times \mathbf{u} &= \mathbf{i}_r \left( \frac{1}{r} \frac{\partial u_z}{\partial\theta} - \frac{\partial u_\theta}{\partial z} \right) + \mathbf{i}_\theta \left( \frac{\partial u_r}{\partial z} - \frac{\partial u_z}{\partial r} \right) + \mathbf{i}_z \left[ \frac{1}{r} \frac{\partial}{\partial r} (ru_\theta) - \frac{1}{r} \frac{\partial u_r}{\partial\theta} \right] \\
\nabla^2\mathbf{u} &= \mathbf{i}_r \left( \nabla^2 u_r - \frac{2}{r^2} \frac{\partial u_\theta}{\partial\theta} - \frac{u_r}{r^2} \right) + \mathbf{i}_\theta \left( \nabla^2 u_\theta + \frac{2}{r^2} \frac{\partial u_r}{\partial\theta} - \frac{u_\theta}{r^2} \right) + \mathbf{i}_z \nabla^2 u_z \\
\nabla\mathbf{u} &= \mathbf{i}_r \mathbf{i}_r \frac{\partial u_r}{\partial r} + \mathbf{i}_r \mathbf{i}_\theta \frac{\partial u_\theta}{\partial r} + \mathbf{i}_r \mathbf{i}_z \frac{\partial u_z}{\partial r} \\
&\quad + \mathbf{i}_\theta \mathbf{i}_r \frac{1}{r} \left( \frac{\partial u_r}{\partial\theta} - u_\theta \right) + \mathbf{i}_\theta \mathbf{i}_\theta \frac{1}{r} \left( \frac{\partial u_\theta}{\partial\theta} + u_r \right) + \mathbf{i}_\theta \mathbf{i}_z \frac{1}{r} \frac{\partial u_z}{\partial\theta} \\
&\quad + \mathbf{i}_z \mathbf{i}_r \frac{\partial u_r}{\partial z} + \mathbf{i}_z \mathbf{i}_\theta \frac{\partial u_\theta}{\partial z} + \mathbf{i}_z \mathbf{i}_z \frac{\partial u_z}{\partial z}
\end{aligned}$$

### 4.2 Spherical

$$\begin{aligned}
\nabla\psi &= \mathbf{i}_R \frac{\partial\psi}{\partial R} + \mathbf{i}_\phi \frac{1}{R} \frac{\partial\psi}{\partial\phi} + \mathbf{i}_\theta \frac{1}{R \sin\phi} \frac{\partial\psi}{\partial\theta} \\
\nabla^2\psi &= \frac{1}{R^2} \left[ \frac{\partial}{\partial R} \left( R^2 \frac{\partial\psi}{\partial R} \right) + \frac{1}{\sin\phi} \frac{\partial}{\partial\phi} \left( \sin\phi \frac{\partial\psi}{\partial\phi} \right) + \frac{1}{\sin^2\phi} \frac{\partial^2\psi}{\partial\theta^2} \right] \\
\nabla \cdot \mathbf{u} &= \frac{1}{R^2} \frac{\partial}{\partial R} (R^2 u_R) + \frac{1}{R \sin\phi} \frac{\partial}{\partial\phi} (\sin\phi u_\phi) + \frac{1}{R \sin\phi} \frac{\partial u_\theta}{\partial\theta} \\
\nabla \times \mathbf{u} &= \mathbf{i}_R \frac{1}{R \sin\phi} \left[ \frac{\partial}{\partial\phi} \left( \sin\phi u_\theta \right) - \frac{\partial u_\phi}{\partial\theta} \right] + \mathbf{i}_\phi \frac{1}{R} \left[ \frac{1}{\sin\phi} \frac{\partial u_R}{\partial\theta} - \frac{\partial}{\partial R} (R u_\theta) \right] + \mathbf{i}_\theta \frac{1}{R} \left[ \frac{\partial}{\partial R} (R u_\phi) - \frac{\partial u_R}{\partial\phi} \right] \\
\nabla^2\mathbf{u} &= \mathbf{i}_R \left[ \nabla^2 u_R - \frac{2}{R^2} \left( u_R + \frac{\partial u_\phi}{\partial\phi} + u_\phi \cot\phi - \frac{1}{\sin\phi} \frac{\partial u_\theta}{\partial\theta} \right) \right] \\
&\quad + \mathbf{i}_\phi \left[ \nabla^2 u_\phi + \frac{1}{R^2} \left( 2 \frac{\partial u_R}{\partial\phi} - \frac{u_\phi}{\sin^2\phi} - 2 \frac{\cos\phi}{\sin^2\phi} \frac{\partial u_\theta}{\partial\theta} \right) \right] \\
&\quad + \mathbf{i}_\theta \left[ \nabla^2 u_\theta + \frac{1}{R^2} \left( \frac{2}{\sin\phi} \frac{\partial u_R}{\partial\theta} + 2 \frac{\cos\phi}{\sin^2\phi} \frac{\partial u_\phi}{\partial\theta} - \frac{u_\theta}{\sin^2\phi} \right) \right] \\
\nabla\mathbf{u} &= \mathbf{i}_R \mathbf{i}_R \frac{\partial u_R}{\partial R} + \mathbf{i}_R \mathbf{i}_\phi \frac{\partial u_\phi}{\partial R} + \mathbf{i}_R \mathbf{i}_\theta \frac{\partial u_\theta}{\partial R} \\
&\quad + \mathbf{i}_\phi \mathbf{i}_R \frac{1}{R} \left( \frac{\partial u_R}{\partial\phi} - u_\phi \right) + \mathbf{i}_\phi \mathbf{i}_\phi \frac{1}{R} \left( \frac{\partial u_\phi}{\partial\phi} + u_R \right) + \mathbf{i}_\phi \mathbf{i}_\theta \frac{1}{R} \frac{\partial u_\theta}{\partial\phi} \\
&\quad + \mathbf{i}_\theta \mathbf{i}_R \frac{1}{R} \left( \frac{1}{\sin\phi} \frac{\partial u_R}{\partial\theta} - u_\theta \right) + \mathbf{i}_\theta \mathbf{i}_\phi \frac{1}{R} \left( \frac{1}{\sin\phi} \frac{\partial u_\phi}{\partial\theta} - \cot\phi u_\theta \right) + \mathbf{i}_\theta \mathbf{i}_\theta \frac{1}{R} \left( \frac{1}{\sin\phi} \frac{\partial u_\theta}{\partial\theta} + u_R + \cot\phi u_\phi \right)
\end{aligned}$$

## 5 Vector Integral Theorems

### 5.1 Gauss's Divergence Theorem

$$\oint\!\oint \mathbf{f} \cdot d\mathbf{S} = \iiint \nabla \cdot \mathbf{f} dV$$

### 5.2 Green's Theorems

#### 5.2.1 Green's First Theorem

$$\oint\!\oint \phi \frac{\partial \psi}{\partial n} dS = \iiint (\phi \nabla^2 \psi + \nabla \phi \cdot \nabla \psi) dV$$

#### 5.2.2 Green's Second Theorem

$$\oint\!\oint \left( \phi \frac{\partial \psi}{\partial n} - \psi \frac{\partial \phi}{\partial n} \right) dS = \iiint (\phi \nabla^2 \psi - \psi \nabla^2 \phi) dV$$

#### 5.2.3 Special Cases

$$\oint\!\oint (\phi \nabla \phi) \cdot d\mathbf{S} = \iiint [\phi \nabla^2 \phi + (\nabla \phi)^2] dV$$

$$\oint\!\oint \frac{\partial \phi}{\partial n} dS = \iiint \nabla^2 \phi dV$$

### 5.3 Stokes' Theorem

Let a simple closed curve  $C$  be spanned by a surface  $S$ . Define the positive normal  $\mathbf{n}$  to  $S$ , and the positive sense of description of the curve  $C$  with line element  $d\mathbf{r}$ , such that the positive sense of the contour  $C$  is clockwise when we look through the surface  $S$  in the direction of the normal. Then, if  $\mathbf{f}$  is continuously differentiable vector field defined on  $S$  and  $C$  with vector element  $\mathbf{S} = \mathbf{n}dS$

$$\oint \mathbf{f} \cdot d\mathbf{r} = \oint\!\oint \nabla \times \mathbf{f} \cdot d\mathbf{S}$$

where the line integral around  $C$  is taken in the positive sense.

### 5.4 Integral rate of change theorems

#### 5.4.1 Rate of change of volume integral bounded by a moving closed surface.

Let  $f$  be a continuous scalar function of position and time  $t$  defined throughout the volume  $V(t)$ , which is itself bounded by a simple closed surface  $S(t)$  moving with velocity  $\mathbf{v}$ . Then the rate of change of the volume integral of  $f$  is given by

$$\frac{D}{Dt} \int_{V(t)} f dV = \int_{V(t)} \frac{\partial f}{\partial t} dV + \int_{S(t)} f \mathbf{v} \cdot d\mathbf{S}$$

where  $d\mathbf{S}$  is the outward drawn vector element of area, and

$$\frac{D}{Dt} \equiv \frac{\partial}{\partial t} + (\mathbf{v} \cdot \nabla)$$

#### 5.4.2 Rate of change of flux through a surface.

Let  $\mathbf{q}$  be a vector function that may also depend on the time  $t$ , and  $\mathbf{n}$  be the unit outward drawn normal to the surface  $S$  that moves with velocity  $\mathbf{v}$ . Defining the flux of  $\mathbf{q}$  through  $S$  as

$$m = \oint_S \mathbf{q} \cdot \mathbf{n} dS$$

then

$$\frac{Dm}{Dt} = \oint \left[ \frac{\partial \mathbf{q}}{\partial t} + \mathbf{v}(\nabla \cdot \mathbf{q}) + \nabla \times (\mathbf{q} \times \mathbf{v}) \right] \cdot \mathbf{n} dS$$

#### 5.4.3 Rate of change of the circulation around a given moving curve.

Let  $C$  be a closed curve, moving with velocity  $\mathbf{v}$ , on which is defined a vector field  $\mathbf{q}$ . Defining the circulation  $\zeta$  of  $\mathbf{q}$  around  $C$  by

$$\zeta = \oint \mathbf{q} \cdot d\mathbf{r}$$

then

$$\frac{D\zeta}{Dt} = \oint \left[ \frac{\partial \mathbf{q}}{\partial t} + (\nabla \times \mathbf{q}) \times \mathbf{v} \right] \cdot d\mathbf{r}$$

## 6 Ideal Flow (irrotational/inviscid/incompressible)

### 6.1 Governing equations

$$\nabla \cdot \mathbf{u} = 0 \quad (\text{continuity})$$

$$\rho \left[ \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right] = -\nabla p \quad (\text{momentum})$$

### 6.2 Fundamentals

#### 6.2.1 Streamfunction

May be defined when continuity eq. reduces to two terms.

For cartesian coordinates:

$$\frac{\partial u}{\partial x} = -\frac{\partial v}{\partial y}$$

The streamfunction may be defined as:

$$u \equiv \frac{\partial \psi}{\partial y} \quad \text{and} \quad v \equiv -\frac{\partial \psi}{\partial x}$$

while vorticity may be defined as

$$\omega_z = -\nabla^2 \psi$$

#### 6.2.2 Velocity potential

$$u \equiv \frac{\partial \phi}{\partial x} \quad \text{and} \quad v \equiv \frac{\partial \phi}{\partial y}$$

#### 6.2.3 Bernoulli's equation

If flow is irrotational throughout:

$$p + \frac{1}{2} \rho V^2 = \text{const.}$$

else, only valid along streamlines.

#### 6.2.4 Incompressible pressure coefficient

$$C_p = 1 - \left( \frac{V}{V_\infty} \right)^2$$

## 7 Viscous Flow

### 7.1 Governing Equations

$$\nabla \cdot \mathbf{u} = 0 \quad (\text{continuity})$$

$$\rho(\mathbf{u} \cdot \nabla \mathbf{u}) = \rho \mathbf{F} - \nabla p + \mu \nabla^2 \mathbf{u} \quad (\text{momentum})$$

### 7.2 Boundary layer terms

#### 7.2.1 Reynolds Numbers

$$Re = \frac{\rho U l}{\mu}$$

#### 7.2.2 Skin friction coefficient

$$C_f(x) = \frac{\tau_w(x)}{\frac{1}{2}\rho U^2}$$

$$= \frac{2}{\sqrt{Re}} \left( \frac{\partial u^*}{\partial y} \right)_w$$

#### 7.2.3 Drag coefficient

$$C_D = \frac{F_D}{\frac{1}{2}\rho U^2 A}$$

$$= b \int_{LE}^{TE} (-p_u \sin \theta + \tau_u \cos \theta) dS_u$$

$$+ b \int_{LE}^{TE} (p_l \sin \theta + \tau_l \cos \theta) dS_l$$

where "u", "l", and "b" denote "upper", "lower", and "width"

#### 7.2.4 Separation point

$$\left( \frac{\partial u}{\partial y} \right)_{y=0} = 0$$

#### 7.2.5 Displacement thickness

$$\delta^* = \int_{y=0}^{\infty} \left( 1 - \frac{u}{U_e} \right) dy$$

#### 7.2.6 Momentum thickness

$$\theta = \int_{y=0}^{\infty} \frac{u}{U_e} \left( 1 - \frac{u}{U_e} \right) dy$$

#### 7.2.7 Shape factor

$$H = \frac{\delta^*}{\theta}$$

### 7.3 Blasius equation

Assumptions:

- Incompressible
- Laminar
- Steady
- $\frac{\partial p}{\partial x} = 0$

#### 7.3.1 Equation

$$f'' + \frac{1}{2} f f'' = 0 \quad \text{where} \quad \eta = \sqrt{vx/U}$$

#### 7.3.2 Shear stress

$$\tau_w = \mu \left( \frac{du}{dy} \right)_{y=0} = 0.332 \rho U^2 / \sqrt{Re_x}$$

#### 7.3.3 Skin friction coefficient

$$C_f \equiv \frac{\tau_w}{\frac{1}{2}\rho U^2} = \frac{0.664}{\sqrt{Re_x}}$$

#### 7.3.4 Drag on plate

$$F_D = \int_0^L \tau_w dx = \frac{0.664 \rho U^2 L}{\sqrt{Re_L}}$$

(drag force per unit width)

#### 7.3.5 Drag coefficient

$$C_D = \frac{F_D}{\frac{1}{2}\rho U^2 L} = \frac{1.33}{\sqrt{Re_L}}$$

### 7.4 Pohlhausen's Polynomial

$$\frac{u(\eta)}{U_\infty} = \left( 2 + \frac{1}{6} \Lambda \right) \eta - \frac{1}{2} \Lambda \eta^2 + \left( \frac{1}{2} \Lambda - 2 \right) \eta^3 + \left( 1 - \frac{1}{6} \Lambda \right) \eta^4$$

where:  $\eta = y/\delta$      $\Lambda = \frac{\rho \delta^2}{\mu} \frac{dU}{dx}$

## 7.5 Von Karman momentum integral equation

$$\tau_w = \rho \left[ \frac{d}{dx} \left( U_e^2 \theta \right) + U_e \delta^* \frac{dU_e}{dx} \right]$$

$$\tau_w = \mu \left. \frac{\partial u}{\partial y} \right|_{y \rightarrow 0}$$

solve for  $\delta(x)$  (boundary layer thickness)

$$C_f = \frac{\tau_w}{\frac{1}{2} \rho U^2} \quad (\text{skin friction coefficient})$$

$$Re = \frac{\rho U \ell}{\mu} \quad \text{and} \quad Re_x = \frac{\rho U x}{\mu}$$

(Reynolds number and x-Reynolds number)

## 7.6 Thwaites' method

For solving Von Karmar mom. int. eq.:

$$\theta^2 = \frac{0.45\nu}{U_e^2(x)} \int_0^x U_e^5(x') dx' + \frac{\theta_0^2 U_0^6}{U_e^6(x)}$$

$$\lambda \equiv \frac{\theta^2}{\nu} \frac{dU_e}{dx} \quad (\text{solve for } \theta)$$

$$\tau \equiv \mu \frac{U_e}{\theta} l(\lambda)$$

$$H(\lambda) = \frac{\delta^*}{\theta}$$

(use table to find surface shear stress and displacement thickness)

# 8 Compressible Flow

## 8.1 Governing equations

$$\frac{\partial}{\partial t} \iiint_V \rho dV + \iint_S \rho \mathbf{u} \cdot d\mathbf{S} = 0 \quad (\text{continuity})$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0$$

$$\frac{\partial}{\partial t} \iiint_V \rho \mathbf{u} dV + \iint_S \rho (\mathbf{u} \cdot d\mathbf{S}) \mathbf{u} = \iiint_V \rho \mathbf{F} dV - \iint_S \rho d\mathbf{S} \quad (\text{momentum})$$

$$\rho \left( \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) = \rho \mathbf{F} - \nabla p$$

## 8.2 General Definitions

### 8.2.1 Mach number

$$M \equiv U/c$$

$$\text{where } c^2 \equiv \left( \frac{\partial p}{\partial \rho} \right)_s$$

$$s_2 - s_1 = c_p \ln \left( \frac{T_2}{T_1} \right) - R \ln \left( \frac{p_2}{p_1} \right)$$

$$= c_v \ln \left( \frac{T_2}{T_1} \right) - R \ln \left( \frac{\rho_2}{\rho_1} \right)$$

### 8.2.2 Compressibility

$$\tau = - \frac{1}{V} \frac{dV}{dp}$$

$$= \frac{1}{\rho} \frac{d\rho}{dp}$$

### 8.2.3 Isothermal compressibility

$$\tau_T = - \frac{1}{V} \left( \frac{\partial V}{\partial p} \right)_T$$

### 8.3.5 Isentropic relations

$$\frac{p_2}{p_1} = \left( \frac{\rho_2}{\rho_1} \right)^\gamma$$

$$\frac{T_2}{T_1} = \left( \frac{\rho_2}{\rho_1} \right)^{\gamma-1} = \left( \frac{p_2}{p_1} \right)^{\frac{\gamma-1}{\gamma}}$$

### 8.3.6 Important air properties

$$R = 287 \text{ m}^2/(\text{s}^2\text{K})$$

$$c_v = 717 \text{ m}^2/(\text{s}^2\text{K})$$

$$c_p = 1004 \text{ m}^2/(\text{s}^2\text{K})$$

$$\gamma = 1.40$$

### 8.2.4 Isentropic compressibility

$$\tau_s = - \frac{1}{V} \left( \frac{\partial V}{\partial p} \right)_s$$

## 8.3 Perfect Gas Thermodynamic Relations

### 8.3.1 Internal Energy/Enthalpy/Thermal eq. of state

$$e = c_v T \quad (\text{internal energy})$$

$$h = c_p T \quad (\text{enthalpy})$$

$$p = \rho RT \quad (\text{thermal equation of state})$$

## 8.4 One-dimensional isentropic flow

### 8.4.1 Continuity

### 8.3.2 Specific heats

$$\rho_1 u_1 A_1 = \rho_2 u_2 A_2$$

$$c_v = \frac{R}{\gamma - 1} \quad c_p = \frac{\gamma R}{\gamma - 1} \quad \gamma = c_p/c_v$$

### 8.4.2 Stagnation enthalpy

### 8.3.3 Speed of sound

$$h_0 = h + \frac{1}{2} u^2 = \text{const.}$$

$$c = \sqrt{\gamma R T} = \sqrt{\gamma p / \rho}$$

### 8.4.3 Stagnation property relations

$$\begin{aligned}\frac{T_0}{T} &= 1 + \frac{\gamma - 1}{2} M^2 \\ \frac{p_0}{p} &= \left(1 + \frac{\gamma - 1}{2} M^2\right)^{\frac{\gamma}{\gamma-1}} \\ \frac{\rho_0}{\rho} &= \left(1 + \frac{\gamma - 1}{2} M^2\right)^{\frac{1}{\gamma-1}}\end{aligned}$$

### 8.4.4 Nozzle area relation

$$\frac{A}{A_*} = \frac{1}{M} \left[ \frac{2}{\gamma + 1} \left(1 + \frac{\gamma - 1}{2} M^2\right) \right]^{\frac{\gamma+1}{2(\gamma-1)}}$$

### 8.4.5 Velocity-area differential relationship

$$\frac{du}{u} = -\frac{1}{1 - M^2} \frac{dA}{A}$$

## 8.5 Normal shock waves

### 8.5.1 Mach number, pressure, temperature, and density relations across a shock

$$\begin{aligned}M_2^2 &= \frac{(\gamma - 1) M_1^2 + 2}{2\gamma M_1^2 + 1 - \gamma} \\ \frac{p_2}{p_1} &= 1 + \frac{2\gamma}{\gamma + 1} (M_1^2 - 1) \\ \frac{\rho_2}{\rho_1} &= \frac{(\gamma + 1) M_1^2}{(\gamma - 1) M_1^2 + 2} \\ \frac{T_2}{T_1} &= 1 + \frac{2(\gamma - 1)}{(\gamma + 1)^2} \frac{\gamma M_1^2 + 1}{M_1^2} (M_1^2 - 1)\end{aligned}$$

### 8.5.2 Entropy change

$$\begin{aligned}\frac{s_2 - s_1}{c_v} &= \ln \left\{ \frac{p_2}{p_1} \left( \frac{\rho_1}{\rho_2} \right)^\gamma \right\} \\ &= \ln \left\{ \left[ 1 + \frac{2\gamma}{\gamma - 1} (M_1^2 - 1) \right] \left[ \frac{(\gamma - 1) M_1^2 + 2}{(\gamma + 1) M_1^2} \right]^\gamma \right\}\end{aligned}$$

## 8.6 Wind Tunnel equations

### 8.6.1 Mass flow rate

$$\dot{m} = \frac{\rho_0 A^*}{T_0} \sqrt{\frac{\gamma}{R} \left( \frac{2}{\gamma + 1} \right)^{\frac{\gamma+1}{\gamma-1}}}$$

### 8.6.2 Nozzle/Diffuser area ratio

$$\begin{aligned}\frac{A_2^*}{A_1^*} &= \frac{p_0}{p'_0} \\ &= \left[ 1 + \frac{2\gamma}{\gamma + 1} (M_1^2 - 1) \right]^{\frac{1}{\gamma-1}} \left[ \frac{(\gamma - 1) M_1^2 + 2}{(\gamma + 1) M_1^2} \right]^{\frac{\gamma}{\gamma-1}}\end{aligned}$$

where  $A_2^*$ ,  $A_1^*$ ,  $p_0$ ,  $p'_0$ , and  $M_1$  are the diffuser throat area, inflow nozzle throat area, stagnation pressure behind the shock, stagnation pressure after the shock, and Mach number upstream of the shock

## 8.7 Two-dimensional compressible flow

### 8.7.1 Definitions

$\delta$  = deflection angle

$\sigma$  = wave angle

$M_1$  = upstream Mach number

$M_2$  = downstream Mach number

### 8.7.2 Mach wave angle

$$\sin \mu = 1/M$$

### 8.7.3 Mach number relation

$$M_2^2 \sin^2 (\sigma - \delta) = \frac{(\gamma - 1) M_1^2 \sin^2 \sigma + 2}{2\gamma M_1^2 \sin^2 \sigma + 1 - \gamma}$$

### 8.7.4 Oblique shockwave angle

$$\tan \delta = 2 \cot \sigma \frac{M_1^2 \sin^2 \sigma - 1}{M_1^2 (\gamma - \cos 2\sigma) + 2}$$

### 8.7.5 Prandtl-Meyer function (expansion fans)

$$\delta_1 + \nu(M_1) = \delta_2 + \nu(M_2) = \text{const.}$$

$$\nu(M) = \sqrt{\frac{\gamma + 1}{\gamma - 1}} \arctan \sqrt{\frac{\gamma - 1}{\gamma + 1} (M^2 - 1)} - \arctan \sqrt{M^2 - 1}$$

## 8.8 Thin-airfoil theory

### 8.8.1 Lift and Drag coefficient

$$\begin{aligned} C_L &= \frac{L}{\frac{1}{2}\rho_\infty U_\infty^2 b} \\ &\approx \frac{4\alpha}{\sqrt{M_\infty^2 - 1}} \\ C_D &= \frac{D}{\frac{1}{2}\rho_\infty U_\infty^2 b} \\ &\approx \frac{4\alpha^2}{\sqrt{M_\infty^2 - 1}} \end{aligned}$$

## 8.9 Velocity Potential

$$\nabla^2 \phi = \frac{1}{2} M_0^2 [(\gamma - 1) \nabla^2 \phi (\nabla \phi \cdot \nabla \phi) + \nabla \phi \cdot \nabla (\nabla \phi \cdot \nabla \phi)]$$

where

$$a^2 = a_0^2 - \frac{\gamma - 1}{2} V^2 = a_0^2 - \frac{\gamma - 1}{2} (u^2 + v^2 + w^2)$$

# 9 Rocket Propulsion Equations

## 9.1 Definitions and Fundamentals

### 9.1.1 Total impulse

$$I_t = \int_0^t F dt \\ = Ft \quad (\text{for constant thrust})$$

### 9.1.2 Specific impulse

$$I_s = I_t / (m_p g_0) \\ = F / (\dot{m} g_0) \\ = F / \dot{w} \\ = I_t / w$$

### 9.1.3 Effective exhaust velocity

$$c = I_s g_0 = F / \dot{m}$$

### 9.1.4 Mass ratio MR

$$m_f / m_0$$

### 9.1.5 Propellant mass fraction $\zeta$

$$\zeta = m_p / m_0 \\ = (m_0 - m_f) / (m_p + m_f)$$

where  $m_0 = m_p + m_f$

### 9.1.6 Impulse-to-weight Ratio

$$\frac{I_t}{w_0} = \frac{I_t}{(m_f + m_p) g_0} = \frac{I_s}{m_f / m_p + 1}$$

### 9.1.7 Thrust $F$

$$F = \frac{d(mv_2)}{dt} = \dot{m}v_2 \quad \text{at sea level} \quad = \frac{\dot{w}}{g_0} v_2 \\ = \dot{m}v_2 + (p_2 - p_3)A_2 \\ = \dot{m}c \\ = \dot{m}v_2 + p_2 A_2 \quad (\text{in vacuum of space}) \\ = F_{\text{opt}} + p_1 A_t \left( \frac{p_2}{p_1} - \frac{p_3}{p_1} \right) \epsilon \\ = \frac{A_t v_t v_2}{V_t} + (p_2 - p_3)A_2 \\ = A_t p_1 \sqrt{\frac{2\gamma^2}{\gamma-1} \left( \frac{2}{\gamma+1} \right)^{\frac{\gamma+1}{\gamma-1}} \left[ 1 - \left( \frac{p_2}{p_1} \right)^{\frac{\gamma-1}{\gamma}} \right]} + (p_2 - p_3)A_2 \\ = C_F A_t p_1 \\ = \dot{m}c^* C_F$$

### 9.1.8 Thrust Coefficient

$$C_F = \frac{F}{p_1 A_t} \\ = \sqrt{\frac{2\gamma^2}{\gamma-1} \left( \frac{2}{\gamma+1} \right)^{\frac{\gamma+1}{\gamma-1}} \left[ 1 - \left( \frac{p_2}{p_1} \right)^{\frac{\gamma-1}{\gamma}} \right]} + \frac{p_2 - p_3}{p_1} \frac{A_2}{A_t}$$

### 9.1.9 Exhaust velocity $c$

$$c = v_2 + (p_2 - p_3) A_2 / \dot{m} = I_s g_0$$

### 9.1.10 Characteristic velocity $c^*$

$$c^* = p_1 A_t / \dot{m} \\ = \frac{I_s g_0}{C_F} \\ = \frac{c}{C_F} \\ = \frac{1}{\gamma} \sqrt{\frac{\gamma R T_1}{\left( \frac{2}{\gamma+1} \right)^{\frac{\gamma+1}{\gamma-1}}}}$$

### 9.1.11 Power of the jet $P_{\text{jet}}$

$$P_{\text{jet}} = \frac{1}{2} \dot{m} v_2^2 = \frac{1}{2} \dot{w} g_0 I_s^2 = \frac{1}{2} F g_0 I_s = \frac{1}{2} F v_2$$

### 9.1.12 Power input to a chemical engine

$$P_{\text{chem}} = \dot{m} Q_R$$

where  $Q_R$  is the heat of combustion per unit of propellant mass.

### 9.1.13 Power transmitted to vehicle

$$P_{\text{vehicle}} = F u \quad (\text{where } u \text{ is vehicle velocity})$$

### 9.1.14 Internal efficiency $\eta_p$

$$\eta_{\text{int}} = \frac{\text{kinetic power in jet}}{\text{available chemical power}} = \frac{\frac{1}{2} \dot{m} v^2}{\eta_{\text{comp}} P_{\text{chem}}}$$

### 9.1.15 Propulsive efficiency

$$\eta_p = \frac{\text{vehicle power}}{\text{vehicle power} + \text{residual kinetic jet power}} \\ = \frac{F u}{F u + \frac{1}{2} \dot{m} (c + u)^2} = \frac{2u/c}{1 + (u/c)^2}$$

### 9.1.16 Multiple propulsion systems

$$\begin{aligned} F_{\text{oa}} &= \sum F = F_1 + F_2 + F_3 + \dots \\ \dot{m}_{\text{oa}} &= \sum \dot{m} = \dot{m}_1 + \dot{m}_2 + \dot{m}_3 + \dots \\ (I_s)_{\text{oa}} &= F_{\text{oa}} / (g_0 \dot{m}_{\text{oa}}) \end{aligned}$$

## 9.2 Nozzle theory and thermodynamic relations

### 9.2.1 Stagnation enthalpy

$$h_0 = h + \frac{1}{2}v^2 = \text{const.}$$

### 9.2.2 Perfect gas law

$$p_x V_x = RT_x$$

### 9.2.3 Specific heats $c$ and their $\gamma$

$$\begin{aligned} k &= c_p/c_v \\ c_p - c_v &= R \\ c_p &= \gamma R / (\gamma - 1) \end{aligned}$$

### 9.2.4 Isentropic flow between $x$ and $y$ in nozzle

$$T_x/T_y = (p_x/p_y)^{\frac{\gamma-1}{\gamma}} = (V_y/V_x)^{\gamma-1}$$

### 9.2.5 Stagnation temperature

$$T_0 = T + \frac{1}{2}v^2/c_p$$

### 9.2.6 Speed of sound & Mach number

$$a = \sqrt{\gamma RT}$$

$$M = v/a = v/\sqrt{\gamma RT}$$

### 9.2.7 Isentropic relations (temperature, Mach number, pressure)

$$\begin{aligned} T_0 &= T \left[ 1 + \frac{1}{2}(\gamma - 1)M^2 \right] \\ M &= \sqrt{\frac{2}{\gamma - 1} \left( \frac{T_0}{T} - 1 \right)} \\ p_0 &= p \left[ 1 + \frac{1}{2}(\gamma - 1)M^2 \right]^{\frac{\gamma}{\gamma-1}} \end{aligned}$$

### 9.2.8 General area ratio

$$\frac{A_y}{A_x} = \frac{M_x}{M_y} \sqrt{\frac{1 + M_y^2(\gamma - 1)/2}{1 + M_x^2(\gamma - 1)/2}}^{\frac{\gamma+1}{\gamma-1}}$$

### 9.2.9 Exit velocity

$$\begin{aligned} v_2 &= \sqrt{2(h_1 - h_2) + v_1^2} \\ &= \sqrt{\frac{2\gamma}{\gamma-1} RT_1 \left[ 1 - \left( \frac{p_2}{p_1} \right)^{(\gamma-1)/\gamma} \right] + v_1^2} \\ &= \sqrt{\frac{2\gamma}{\gamma-1} RT_1 \left[ 1 - \left( \frac{p_2}{p_1} \right)^{(\gamma-1)/\gamma} \right]} \quad (\text{when } v_1 \approx 0 \text{ (chamber)}) \\ &= \sqrt{\frac{2\gamma}{\gamma-1} \frac{RT_1}{M} \left[ 1 - \left( \frac{p_2}{p_1} \right)^{(\gamma-1)/\gamma} \right]} \end{aligned}$$

where  $M$  is molecular mass.

### 9.2.10 Critical/Throat velocity

$$v_t = \sqrt{\frac{2\gamma}{\gamma+1} RT_1} = \sqrt{\gamma RT_t} = a_t$$

### 9.2.11 Mass flow rate

$$\dot{m} = \frac{A_t v_t}{V_t} = A_t p_1 \gamma \sqrt{\frac{\left(\frac{2}{\gamma+1}\right)^{\frac{\gamma+1}{\gamma-1}}}{\gamma RT_1}}$$

### 9.2.12 Ratio between throat and downstream area with pressure $p_y$

$$\frac{A_t}{A_y} = \frac{V_t v_y}{V_y v_t} = \left( \frac{\gamma+1}{2} \right)^{\frac{1}{\gamma-1}} \left( \frac{p_y}{p_1} \right)^{1/\gamma} \sqrt{\frac{\gamma+1}{\gamma-1} \left[ 1 - \left( \frac{p_y}{p_1} \right)^{\frac{\gamma-1}{\gamma}} \right]}$$

### 9.2.13 Velocity of downstream point from throat

$$\frac{v_y}{v_t} = \sqrt{\frac{\gamma+1}{\gamma-1}}$$

### 9.2.14 Cone-shaped nozzle correction factor for exhaust velocity

$\gamma = \frac{1}{2}(1 + \cos \alpha)$        $\alpha = 15^\circ$  cone is accepted standard where  $\alpha$  is the cone angle.

### 9.2.15 Rocket Equation

$$e^{\Delta u/c} = 1/MR = m_0/m_f$$

## 9.3 Chemical Rocket Performance Analysis

### 9.3.1 Mol fraction

$$X_j = \frac{n_j}{n} \quad \text{and} \quad n = \sum_{j=1}^m n_j$$

### 9.3.2 Effective average molecular mass

$$\bar{M} = \frac{\sum_{j=1}^m n_j M_j}{\sum_{j=1}^m n_j}$$

### 9.3.3 Molar specific heat and specific heat ratio

$$\begin{aligned}(C_p)_{\text{mix}} &= \frac{\sum_{j=1}^m n_j (C_p)_j}{\sum_{j=1}^m n_j} \\ \gamma_{\text{mix}} &= \frac{(C_p)_{\text{mix}}}{(C_p)_{\text{mix}} - R'}\end{aligned}$$

### 9.3.4 Heat of reaction

$$\Delta_r H^0 = \sum [n_j (\Delta_f H^0)]_{\text{products}} - \sum [n_j (\Delta_f H^0)]_{\text{reactants}}$$

### 9.3.5 Gibbs free energy

$$G = \sum_{j=1}^m n_j G_j$$

$$G_j = U_j + p_j V_j - T_j S_j = h_j - T_j S_j$$

$$\Delta_r G^0 = \sum_{j=1}^m [n_j (\Delta_f G^0)]_{\text{products}} - \sum_{j=1}^r [n_j (\Delta_f G^0)]_{\text{reactants}}$$

### 9.3.6 Heat of reaction

$$\Delta_r H = \sum_1^m n_j \int_{T_{\text{ref}}}^{T_1} C_{pj} dT = \sum_1^m n_j \Delta h_j \Big|_{T_{\text{ref}}}^{T_1}$$

## 9.4 Solid Propellant Rocket Motor Fundamentals

### 9.4.1 Mass flow rate

$$\begin{aligned}\dot{m} &= A_b r \rho_b \\ &= \frac{d(\rho_1 V_1)}{dt} + \frac{A_t p_1}{c^*} \\ &= A_b \rho_b a p_1^n\end{aligned}$$

where  $A_b$ ,  $r$ , and  $\rho_b$  are the burn area, burn rate, and density of solid propellant before burning

### 9.4.2 Pressure in steady burning

$$p_1 = K \rho_b r c^* \quad \text{where} \quad K \equiv A_b / A_t$$

### 9.4.3 Burning rate approximation

$$r = a p_1^n$$

# 10 Aeroacoustics

## 10.1 Governing Equations

$$\frac{\partial p'}{\partial t} + \rho_0 \nabla \cdot \mathbf{u}' = 0 \quad (\text{continuity})$$

$$\rho_0 \frac{\partial \mathbf{u}'}{\partial t} = -\nabla p' \quad (\text{momentum})$$

## 10.2 General definitions

$$k = \frac{2\pi}{\lambda} = \frac{\omega}{a_0} = \frac{2\pi f}{a_0} = \frac{2\pi}{a_0 T} \quad (\text{waves/distance})$$

$$\lambda = \frac{2\pi}{k} = \frac{\omega}{2\pi a_0} = \frac{a_0}{f} = a_0 T \quad (\text{distance/wave})$$

$$\omega = a_0 k = \frac{2\pi a_0}{\lambda} = 2\pi f = \frac{2\pi}{T} \quad (\text{radians/second})$$

$$a_0 = \frac{\omega}{k} = \lambda f = \frac{2\pi f}{k} = \frac{2\pi}{kT} \quad (\text{distance/time})$$

$$f = \frac{a_0 k}{2\pi} = \frac{a_0}{\lambda} = \frac{\omega}{2\pi} = \frac{1}{T} \quad (\text{wavelength/time})$$

$$T = \frac{a_0 k}{2\pi} = \frac{\lambda}{a_0} = \frac{2\pi}{\omega} = \frac{1}{f} \quad (\text{time/wavelength})$$

### 10.2.1 D'Alembert Solution (plane wave)

$$f(x, t) = F(x - a_0 t) + G(x + a_0 t)$$

### 10.2.2 Fourier Series

$$f(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} \left[ a_n \cos\left(\frac{2\pi n t}{T}\right) + b_n \sin\left(\frac{2\pi n t}{T}\right) \right]$$

$$a_0 = \frac{2}{T} \int_0^T f(t) dt$$

$$a_n = \frac{2}{T} \int_0^T f(t) \cos\left(\frac{2\pi n t}{T}\right) dt$$

$$b_n = \frac{2}{T} \int_0^T f(t) \sin\left(\frac{2\pi n t}{T}\right) dt$$

$$f(t) = \sum_{n=-\infty}^{\infty} c_n e^{i \frac{2\pi n t}{T}}$$

$$c_n = \frac{1}{T} \int_0^T f(t) e^{i \frac{2\pi n t}{T}} dt$$

$$c_n = \begin{cases} \frac{a_{-n} + i b_{-n}}{2}; & n \leq -1 \\ \frac{a_0}{2} & n = 0 \\ \frac{a_n - i b_n}{2} & n \geq 1 \end{cases}$$

### 10.2.3 Fourier Transform

$$\tilde{f}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(t) e^{-i\omega t} dt \quad (\text{fourier transform})$$

$$f(t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \tilde{f}(\omega) e^{i\omega t} d\omega \quad (\text{inverse fourier transform})$$

### 10.2.4 Acoustic Intensity

$$\mathbf{I} = p' \mathbf{u}'$$

$$\langle I \rangle = \frac{A^2}{2\rho_0 a_0} \quad \text{Units: } \left[ \frac{\text{W}}{\text{m}^2} \right]$$

### 10.2.5 Acoustic Energy

$$e = \frac{p'^2}{2\rho_0 a_0^2} + \frac{1}{2} \rho_0 \mathbf{u}'^2$$

$$\langle e \rangle = \frac{A^2}{2\rho_0 a_0^2} \quad \text{Units: } \left[ \frac{\text{J}}{\text{m}^2} \right] \quad (\text{energy density})$$

### 10.2.6 Root of Square Average (RMS)

$$p'_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T p(t)^2 dt}$$

$$= \frac{A}{\sqrt{2}} \quad (\text{for } p(t)' = A \cos t)$$

### 10.2.7 Decibel

$$10 \log_{10} \left( \frac{\text{Power}}{\text{Ref power}} \right)$$

### 10.2.8 Acoustic Power Level

$$\text{APL} = 10 \log_{10} \left( \frac{\mathbb{P}_{\text{acoustic}}}{\mathbb{P}_{\text{ref}}} \right) \quad [\text{dB}]$$

$$\mathbb{P} = \mathbb{P}_{\text{ref}} 10^{\text{APL}/10}$$

where  $\mathbb{P}_{\text{ref}} = 10^{-12} \text{ [W]}$  and  $\mathbb{P} = \langle I \rangle A$

where  $A$  is the area the sound is going through

### 10.2.9 Sound Pressure Level

$$\text{SPL} = 10 \log_{10} \left( \frac{p'_{\text{rms}}^2}{p_{\text{ref}}^2} \right)$$

$$= 20 \log_{10} \left( \frac{p_{\text{rms}}}{p_{\text{ref}}} \right)$$

$$p_{\text{ref}} = 2 \times 10^{-5} \text{ [Pa]}$$

### 10.2.10 RMS pressure summation

$$(p_{\text{rms}})_{1+2} = \sqrt{(p_{\text{rms}})_1^2 + (p_{\text{rms}})_2^2} \quad (1)$$

### 10.2.11 SPL summation

$$\text{SPL}_{1+2+\dots+n} = 10 \log_{10} \left( 10^{\text{SPL}_1/10} + 10^{\text{SPL}_2/10} + \dots + 10^{\text{SPL}_n/10} \right) \quad (2)$$

### 10.2.12 Impedance

$$\begin{aligned} Z &= i\sigma\omega \\ &= \rho_0 a_0 \\ &= \frac{p'}{u'} \\ m/A &= \sigma \quad (\text{mass/area}) \end{aligned}$$

### 10.2.13 Planar wave transmission & reflection

$$\begin{aligned} p_t &= \frac{2\rho_0 a_0}{2\rho_0 a_0 + i\sigma\omega} p_i && \text{(transmission)} \\ p_r &= \frac{i\sigma\omega}{2\rho_0 a_0 + i\sigma\omega} p_i && \text{(reflection)} \\ \text{where } \sigma &= m/A \end{aligned}$$

### 10.2.14 Reflection/Transmission coefficient

$$\begin{aligned} \alpha_r &\equiv \frac{\langle I \rangle_r}{\langle I \rangle_i} \\ \alpha_t &\equiv \frac{\langle I \rangle_t}{\langle I \rangle_i} \end{aligned}$$

### 10.2.15 Composite surface transmission coefficient

$$\alpha_{t_{\text{eff}}} = \frac{\sum_{j=1}^n \alpha_j A_j}{A_T} \quad \text{where } A \text{ is surface area}$$

### 10.2.16 Transmission loss

$$\begin{aligned} \text{T.L.} &= 10 \log \left( \frac{1}{\alpha_t} \right) \\ &= 10 \log \left[ \frac{(\sigma\omega)^2}{(2\rho_0 a_0)^2} \right] + 10 \log \left[ 1 + \frac{(2\rho_0 a_0)^2}{(\sigma\omega)^2} \right] \end{aligned}$$

### 10.2.17 Spherical wave equation

$$p = \frac{A}{r} e^{i(\omega t - kr)}$$

### 10.2.18 Spherical Sound Pressure Level

$$\begin{aligned} SPL &= 20 \log \left( \frac{p_{\text{rms}}}{p_{\text{ref}}} \right) \\ &= 20 \log \left( \frac{A}{\sqrt{2} p_{\text{ref}}} \right) - 20 \log(r) \end{aligned}$$

$$\Delta_{\text{SPL}} = \text{SPL}_1 - \text{SPL}_2 = 20 \log \left( \frac{r_2}{r_1} \right)$$

### 10.2.19 Spherical acoustic velocity

$$\begin{aligned} u'_r &= \frac{p'(t)}{\rho_0 a_0} \left( 1 + \frac{1}{ikr} \right) \\ &= \frac{A}{\rho_0 a_0 r} \left( 1 + \frac{1}{ikr} \right) e^{i(\omega t - kr)} \end{aligned}$$

### 10.2.20 Reverberant Field energy density

$$\begin{aligned} \langle e \rangle_{\text{RF}} &= \frac{4\pi p_{\text{rms}}^2}{\rho_0 a_0^2} \\ &= \frac{2\pi A^2}{\rho_0 a_0^2} \end{aligned}$$

### 10.2.21 Reverberant field intensity

$$\begin{aligned} \langle I \rangle_{\text{RF}} &= \frac{\pi A^2}{2\rho_0 a_0} \\ &= \frac{\langle e \rangle_{\text{RF}} a_0}{4} \end{aligned}$$

### 10.2.22 Absorption

$$\begin{aligned} \langle I \rangle_{\text{RF}} &= \frac{\mathbb{P} (1 - \alpha_A)}{\alpha_A A_{\text{wall}}} = \frac{\mathbb{P}}{R} \\ \alpha_A &= \frac{\langle I \rangle_a}{\langle I \rangle_i} = \frac{\langle I \rangle_i - \langle I \rangle_r}{\langle I \rangle_i} \end{aligned}$$

### 10.2.23 Reverberant Field SPL

$$\begin{aligned} \text{SPL}_{\text{RF}} &= 10 \log_{10} \left[ \frac{(p_{\text{rms}}^2)_{\text{RF}}}{p_{\text{ref}}^2} \right] \\ &= 10 \log \left( \frac{4\rho_0 a_0 \mathbb{P}}{R p_{\text{ref}}^2} \right) \\ R &= \frac{A_{\text{wall}} \alpha_A}{(1 - \alpha_A)} \end{aligned}$$

### 10.2.24 Direct field and Total SPL

$$\text{SPL}_{\text{total}} = 10 \log_{10} \left( \frac{\rho_0 a_0 \mathbb{P}}{p_{\text{ref}}^2} \right) + 10 \log_{10} \left( \frac{1}{4\pi r^2} + \frac{4}{R} \right)$$

### 10.2.25 Average absorption coefficient

$$\alpha_A = \frac{\sum \alpha_{A_i} A_i}{\sum A_i}$$

### 10.2.26 Average SPL or "equivalent level"

$$\text{SPL}_{\text{AVG}} = L_{\text{EQ}} = 10 \log_{10} \left( \frac{1}{T} \sum_{i=1}^N 10^{\text{SPL}_i/10} \Delta t_i \right)$$

### 10.2.27 Day/Night level

$$L_{\text{DN}} = 10 \log_{10} \left[ \frac{1}{T} \left( \sum_{0700}^{2200} 10^{\text{SPL}(t)/10} \Delta t_i + \sum_{2200}^{0700} 10^{\frac{\text{SPL}(10)+10}{10}} \Delta t_i \right) \right]$$

#### 10.2.28 Permissible time & dose

$$T = \frac{8}{2^{\frac{L-90}{5}}}$$
$$D = \sum_{i=1}^N \frac{A_i}{T} = \frac{1}{8} \sum_{i=1}^N \Delta t_i 2^{\frac{L_i-90}{5}} \leq 1$$

$A_i$  is the actual time

$T$  is the permissible time (8 hours at 90 dB)

# 11 Flight Dynamics

## 11.1 Introduction and Notation

### Particle kinematics in rotating frame

$$\begin{aligned}\mathbf{A} &= \mathbf{A}(t) \\ \frac{d\mathbf{A}}{dt} &= \frac{\delta\mathbf{A}}{\delta t} + \boldsymbol{\omega} \times \mathbf{A} \\ \frac{d^2\mathbf{A}}{dt^2} &= \frac{\delta^2\mathbf{A}}{\delta t^2} + 2\boldsymbol{\omega} \times \frac{\delta\mathbf{A}}{\delta t} + \frac{\delta\boldsymbol{\omega}}{\delta t} \times \mathbf{A} + \boldsymbol{\omega} \times \boldsymbol{\omega} \times \mathbf{A} \\ \frac{d^3\mathbf{A}}{dt^3} &= \frac{\delta^3\mathbf{A}}{\delta t^3} + 3\left(\frac{\delta\boldsymbol{\omega}}{\delta t} \times \frac{\delta\mathbf{A}}{\delta t} + \boldsymbol{\omega} \times \frac{\delta^2\mathbf{A}}{\delta t^2} + \boldsymbol{\omega} \times \boldsymbol{\omega} \times \frac{\delta\mathbf{A}}{\delta t}\right) \\ &\quad + \frac{\delta^2\boldsymbol{\omega}}{\delta t^2} \times \mathbf{A} + \boldsymbol{\omega} \times \frac{\delta\boldsymbol{\omega}}{\delta t} \times \mathbf{A} + \boldsymbol{\omega} \times \boldsymbol{\omega} \times \boldsymbol{\omega} \times \mathbf{A}\end{aligned}$$

where  $\mathbf{A}$  and  $\boldsymbol{\omega}$  are the vector and angular velocity vector in the rotating frame.

### Rigid body equations of motion (body-fixed frame)

$$\begin{aligned}\dot{u} &= F_x/m - g \sin \theta + rv - qw \\ \dot{v} &= F_y/m + g \sin \phi \cos \theta - ru + pw \\ \dot{w} &= F_z/m + g \cos \phi \cos \theta + qu - pv \\ \dot{p} &= \frac{I_{zz}M_x + I_{xz}M_z + I_{xz}(I_{xx} - I_{yy} + I_{zz})pq - (I_{xz}^2 - I_{yy}I_{zz} + I_{zz}^2)qr}{I_{xx}I_{zz} - I_{xz}^2} \\ \dot{q} &= \frac{M_y - I_{xz}p^2 + (I_{zz} - I_{xx})pr + I_{xz}r^2}{I_{yy}} \\ \dot{r} &= \frac{I_{xz}M_x + I_{xx}M_z + (I_{xx}^2 + I_{xz}^2 - I_{xx}I_{yy})pq - I_{xz}(I_{xx} - I_{yy} + I_{zz})qr}{I_{xx}I_{zz} - I_{xz}^2}\end{aligned}$$

Where  $u, v, w, p, q, r, \phi, \theta$ , and  $\psi$  are the velocities in the  $x, y$ , and  $z$  directions and the angular accelerations in  $x, y$ , and  $z$  directions.

### Aerodynamic Forces and Moments:

$$\begin{aligned}C_D &\equiv \text{drag coefficient} \equiv \frac{D}{\frac{1}{2}\rho_\infty V_\infty^2 S} \\ C_L &\equiv \text{lift coefficient} \equiv \frac{L}{\frac{1}{2}\rho_\infty V_\infty^2 S} \\ C_A &\equiv \text{axial force coefficient} \equiv \frac{A}{\frac{1}{2}\rho_\infty V_\infty^2 S} \\ C_N &\equiv \text{normal force coefficient} \equiv \frac{N}{\frac{1}{2}\rho_\infty V_\infty^2 S} \\ C_m &\equiv \text{pitching moment coefficient} \equiv \frac{m}{\frac{1}{2}\rho_\infty V_\infty^2 Sc}\end{aligned}$$

### Aerodynamic Forces and Moments per unit span (2-D):

$$\begin{aligned}\tilde{C}_D &\equiv \text{drag coefficient} \equiv \frac{\tilde{D}}{\frac{1}{2}\rho_\infty V_\infty^2 c} \\ \tilde{C}_L &\equiv \text{lift coefficient} \equiv \frac{\tilde{L}}{\frac{1}{2}\rho_\infty V_\infty^2 c} \\ \tilde{C}_A &\equiv \text{axial force coefficient} \equiv \frac{\tilde{A}}{\frac{1}{2}\rho_\infty V_\infty^2 c} \\ \tilde{C}_N &\equiv \text{normal force coefficient} \equiv \frac{\tilde{N}}{\frac{1}{2}\rho_\infty V_\infty^2 c} \\ \tilde{C}_m &\equiv \text{pitching moment coefficient} \equiv \frac{\tilde{m}}{\frac{1}{2}\rho_\infty V_\infty^2 c^2}\end{aligned}$$

### Angle of attack relations:

$\alpha \equiv$  the angle from  $\mathbf{V}_\infty$  to the chord line (positive nose up)

$$\begin{aligned}\tilde{C}_L &= \tilde{C}_N \cos \alpha - \tilde{C}_A \sin \alpha \\ \tilde{C}_D &= \tilde{C}_A \cos \alpha + \tilde{C}_N \sin \alpha \\ \tilde{C}_N &= \tilde{C}_L \cos \alpha + \tilde{C}_D \sin \alpha \\ \tilde{C}_A &= \tilde{C}_D \cos \alpha - \tilde{C}_L \sin \alpha\end{aligned}$$

## 11.2 Aircraft Performance

### 11.2.1 Thrust required

$$T_R = \frac{W}{(L/D) \cos \alpha_T + \sin \alpha_T} \quad (\text{Thrust})$$

$$D = T_R \cos \alpha_T \quad (\text{Total Drag})$$

$$= \frac{1}{2} \rho V^2 S_W C_D$$

$$= \frac{1}{2} \rho V^2 S_W \left( C_{D_0} + C_{D_0,L} C_L + \frac{C_L^2}{\pi e R_A} \right)$$

$$C_{D_0} = \frac{C_L^2}{\pi e R_A} \quad (\text{Induced Drag})$$

$$L = W - T_R \sin \alpha_T \quad (\text{Lift})$$

$$C_L = \frac{L}{\frac{1}{2} \rho V^2 S_W} = \frac{W - T_R \sin \alpha_T}{\frac{1}{2} \rho V^2 S_W} \quad (\text{Lift Coefficient})$$

$$= \frac{W}{\frac{1}{2} \rho V^2 S_W} \left[ \frac{1}{1 + (D/L) \tan \alpha_T} \right]$$

$$\frac{L}{D} = \frac{W - T_R \sin \alpha_T}{T_R \cos \alpha_T} \quad (\text{Lift-Drag ratio})$$

$$= \frac{C_L}{C_D} = \frac{C_L}{C_{D_0} + C_{D_0,L} C_L + \frac{C_L^2}{\pi e R_A}}$$

$$(L/D)_{\max} = \frac{\sqrt{\pi e R_A}}{2 \sqrt{C_{D_0} + C_{D_0,L} \sqrt{\pi e R_A}}} \quad (\text{Max Lift/Drag})$$

$$V_{MD} = \frac{\sqrt{2}}{(\pi e R_A C_{D_0})^{1/4}} \sqrt{\frac{W/S_W}{\rho}}$$

$$\times \sqrt{\left[ 1 + \left( 2 \sqrt{\frac{C_{D_0}}{\pi e R_A}} + C_{D_0,L} \right)^{-1} \tan \alpha_T \right]} \quad (\text{Minimum drag airspeed})$$

## Small-angle approximation aircraft performance

$$T_R = D \quad (\text{Thrust})$$

$$= \frac{W}{L/D}$$

$$= \frac{C_D}{C_L} W$$

$$= \left( \frac{C_{D_0}}{C_L} + C_{D_0,L} + \frac{C_L}{\pi e R_A} \right) W$$

$$= \left( \frac{\frac{1}{2} \rho V^2 C_{D_0}}{W/S_W} + C_{D_0,L} + \frac{W/S_W}{\frac{1}{2} \pi e R_A \rho V^2} \right) W$$

$$L = W \quad (\text{Lift})$$

$$C_L = \frac{W}{\frac{1}{2} \rho V^2 S_W} \quad (\text{Lift Coefficient})$$

$$V_{MD} = \left( \frac{4}{\pi e R_A C_{D_0}} \right)^{1/4} \sqrt{\frac{W/S_W}{\rho}} \quad (\text{Minimum drag airspeed})$$

## 11.3 Longitudinal Static Stability and Trim

### 11.3.1 Pitch Stability of a Cambered Wing

$$T = D \quad (\text{Thrust})$$

$$L = W \quad (\text{Lift})$$

*Pitching moment about center of gravity*

$$m = m_{ac} - l_w L = 0$$

$$C_m = C_{m_{ac}} - \frac{l_w}{c} C_L = 0$$

*Pitch Stability*

$$\frac{\partial C_m}{\partial \alpha} \equiv C_{m,\alpha} < 0$$

### 11.3.2 Simplified Pitch Stability Analysis for a Wing-Tail Combination

# 12 Classical Mechanics

## 12.1 Newton's Laws

### 12.1.1 First Law

In the absence of forces, a particle moves with constant velocity  $\mathbf{V}$ .

### 12.1.2 Second Law

$$\mathbf{F} = \frac{d\mathbf{p}}{dt} \equiv \dot{\mathbf{p}} = \frac{d}{dt}(m\mathbf{v})$$

### 12.1.3 Third Law

If object 1 exerts a force  $\mathbf{F}_{12}$  on object 2, then object 2 always exerts a reaction force  $\mathbf{F}_{21}$  on object 1 given by

$$\mathbf{F}_{12} = -\mathbf{F}_{21}$$

## 12.2 Angular Momentum for a single particle

$$\mathbf{l} = \mathbf{r} \times \mathbf{p}$$

$$\dot{\mathbf{l}} = (\dot{\mathbf{r}} \times \mathbf{p}) + (\mathbf{r} \times \dot{\mathbf{p}})$$

## 12.3 Kinetic Energy and Work

### 12.3.1 Kinetic Energy

$$T = \frac{1}{2}mv^2$$

$$\frac{dT}{dt} = m\dot{\mathbf{v}} \cdot \mathbf{v} = \mathbf{F} \cdot \mathbf{v}$$

$$dT = \mathbf{F} \cdot d\mathbf{r}$$

### 12.3.2 Work

$$W_{1 \rightarrow 2} = \int_1^2 \mathbf{F} \cdot d\mathbf{r}$$

## 12.4 Rotational Motion of rigid bodies

### 12.4.1 Center of Mass

$$\mathbf{R} = \frac{1}{M} \oint \rho \mathbf{r} dV$$

$$dV = dx dy dz$$

### 12.4.2 Momentum

$$\mathbf{P} = M\dot{\mathbf{R}}$$

### 12.4.3 Angular Momentum

$$\mathbf{L} = \mathbf{I}\boldsymbol{\omega}$$

$$\begin{aligned} L_x &= I_{xx}\omega_x + I_{xy}\omega_y + I_{xz}\omega_z \\ L_y &= I_{yx}\omega_x + I_{yy}\omega_y + I_{yz}\omega_z \\ L_z &= I_{zx}\omega_x + I_{zy}\omega_y + I_{zz}\omega_z \end{aligned}$$

### 12.4.4 Inertia tensor

$$\begin{aligned} I_{ik} &= \oint \rho [(\mathbf{r} \cdot \mathbf{r}) \delta_{ik} - x_i x_k] dV \\ &= \begin{bmatrix} \int \rho (y^2 + z^2) dV & -\int \rho xy dV & -\int \rho xz dV \\ -\int \rho yx dV & \int \rho (x^2 + z^2) dV & -\int \rho yz dV \\ -\int \rho zx dV & -\int \rho zy dV & \int \rho (x^2 + y^2) dV \end{bmatrix} \\ dV &= dx dy dz \end{aligned}$$

## 12.5 Special Relativity

$$\gamma(v) = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

### Relativistic values

$$m = \gamma m_0$$

$$\mathbf{p} = \gamma m_0 \mathbf{v}$$

$$E = \gamma m_0 c^2$$

$$K = m_0 c^2 (\gamma - 1)$$

### Lorentz-Einstein transformations

$$\begin{aligned} x' &= \gamma(x - vt) & x &= \gamma(x' + vt') \\ y' &= y & y &= y' \\ z' &= z & z &= z' \\ t' &= \gamma(t - vx/c^2) & t &= \gamma(t' + vx'/c^2) \end{aligned}$$

### Lorentz contraction

$$l = l_0/\gamma$$

### Velocity transformation

$$\begin{aligned} u_x &= \frac{u'_x + v}{1 + vu'_x/c^2} & u'_x &= \frac{u_x - v}{1 - vu_x/c^2} \\ u_y &= \frac{u'_y + v}{1 + vu'_y/c^2} & u'_y &= \frac{u_y - v}{1 - vu_y/c^2} \end{aligned}$$

### Relativistic doppler shift

$$\beta = v/c$$

$$\lambda' = \frac{\lambda}{\gamma(1 + \beta \cos \theta)}$$

$$\lambda = \lambda \gamma (1 - \beta \cos \theta')$$

# 13 Thermodynamics & Statistical Mechanics

## 13.1 Quantum Effects

**Electrical Charge:**

$$e = 1.602 \times 10^{-19} \text{ C}$$

**Wavelength of particle waves:**

$$\lambda = \frac{h}{p}$$

where  $h$  is Plank's constant and  $p$  is the particle's momentum.

$$p = \frac{h}{\lambda} = \frac{h}{2\pi} \frac{2\pi}{\lambda} = \hbar k$$

**Uncertainty Principle:**

$$\Delta x \Delta p_x = h$$

$$\Delta y \Delta p_y = h$$

$$\Delta z \Delta p_z = h$$

$$\Delta \theta \Delta L = h$$

**Area of accessible states:**

$$\text{number of accessible states} = \frac{\text{total area}}{\text{area of one state}} = \frac{[x][p_x]}{h}$$

In three dimensions:

$$\text{number of accessible states} = \frac{V_r V_p}{h^3} = \frac{\int dx dy dz dp_x dp_y dp_z}{h^3}$$

**Density of states for system of noninteracting particles:**

$$g(\epsilon) = \frac{2\pi V(2m)^{3/2}}{h^3} \sqrt{\epsilon} \quad \text{nonrelativistic gas}$$

$$g(\epsilon) = \frac{4\pi V}{h^3 c^3} \epsilon^2 \quad \text{massless or relativistic gas}$$

**Angular momentum:**

$$\mathbf{J} = \mathbf{L} + \mathbf{S}$$

where  $\mathbf{J}$ ,  $\mathbf{L}$ , and  $\mathbf{S}$  is the total angular momentum, orbital spin, and that due to intrinsic spin. **Orbital angular momentum**

$$|\mathbf{L}| = \sqrt{l(l+1)\hbar}$$

where  $l$  is the "angular momentum quantum number."

**$z$ -angular momentum**

$$L_z = l_z \hbar, \quad l_z = 0, \pm 1, \pm 2, \dots, \pm l$$

**Intrinsic spin angular momentum  $\mathbf{S}$ :**

$$|\mathbf{S}| = \sqrt{s(s+1)\hbar}$$

$$S_z = s_z \hbar \quad s_z = -s, -1+s, \dots, +s$$

Those with integer spin are "bosons." Those with half-integer spins are fermions

**Magnetic moment  $\mu$**

$$\mu = \left( \frac{q}{2m} \right) \mathbf{L}$$

$$\mu_z = \left( \frac{q}{2m} \right) L_z, \quad L_z = (0, \pm 1, \pm 2, \dots, \pm l) \hbar$$

where  $q$  is the charge of the particle and  $m$  is its mass.

**Spin angular momentum  $\mathbf{S}$ :**

$$\mu = g \left( \frac{e}{2m} \right) \mathbf{S} \quad \mu_z = g \left( \frac{e}{2m} \right) S_z$$

where  $e$  is the fundamental charge and  $g$  is the "gyromagnetic ratio."

**Gyromagnetic moment  $g$  values**

$$g = -2.00 \quad \text{electron}$$

$$g = +5.58 \quad \text{proton}$$

$$g = -3.82 \quad \text{neutron}$$

**Interaction of  $\mu$  with  $\mathbf{B}$ :**

$$U = -\mu \cdot \mathbf{B}$$

**Harmonic oscillator potential:**

$$E = \left( n + \frac{1}{2} \right) \hbar \omega, \quad n = 0, 1, 2, \dots$$

$$\omega = \sqrt{\frac{\kappa}{m}} \quad (\text{3-D harmonic oscillator})$$

## 13.2 Probabilities for various configurations

### 13.2.1 One criterion

**Probability of  $n$  of  $N$  particles satisfying 1 criterion:**

$$P_N(n) = \frac{N!}{n!(N-n)!} p^n q^{N-n}$$

**Number of such configurations:**

$$\text{number of such configurations} = \frac{N!}{n!(N-n)!}$$

### 13.2.2 Handling factorials

**Stirling's approximation**

$$m! \approx \sqrt{2\pi m} \left( \frac{m}{e} \right)^m$$

$$\ln m! \approx m \ln m - m + \frac{1}{2} \ln(2\pi m)$$

### 13.2.3 Many criteria

**Probability  $n_1, n_2, \dots, n_m$  particles will satisfy  $m$  criteria from  $N$  particles:**

$$P_N(n_1, n_2, \dots, n_m) = \frac{N}{n_1! n_2! \dots n_m!} p_1^{n_1} p_2^{n_2} \dots p_m^{n_m}$$

### 13.3 Systems with many elements

#### 13.3.1 Mean value and standard deviation

##### Average number of particle $\bar{n}$ satisfying 1 criterion

$$\bar{n} = pN$$

where  $p$  is the probability for any given element to satisfy the criterion.

##### Standard deviation

$$\sigma = \sqrt{Npq}$$

$$\frac{\sigma}{\bar{n}} = \sqrt{\frac{q}{Np}} \approx \frac{1}{\sqrt{N}}$$

#### 13.3.2 The random walk

##### Total distance travelled:

$$S_N = \sum_{i=1}^N$$

##### Standard deviation after $N$ steps:

$$\sigma_N = \sqrt{N}\sigma$$

where  $\sigma$  is the standard deviation of a single step.

### 13.4 Internal energy

#### Potential well $u_0$ :

$$u_0 = u_0(T, p, N)$$

#### Energy in solids:

$$\begin{aligned} \epsilon &= \epsilon_{\text{potential}} + \epsilon_{\text{kinetic}} \\ &= u_0 + \frac{1}{2}\kappa x^2 + \frac{1}{2}\kappa y^2 + \frac{1}{2}\kappa z^2 + \frac{1}{2m}p_x^2 + \frac{1}{2m}p_y^2 + \frac{1}{2m}p_z^2 \end{aligned}$$

#### Energy in liquids:

$$\begin{aligned} \epsilon &= \epsilon_{\text{potential}} + \epsilon_{\text{kinetic}} \\ &= u_0 + \frac{1}{2m}p_x^2 + \frac{1}{2m}p_y^2 + \frac{1}{2m}p_z^2 \end{aligned}$$

#### Energy in gases:

$$\begin{aligned} \epsilon &= \epsilon_{\text{kinetic}} \\ &= \frac{1}{2m}p_x^2 + \frac{1}{2m}p_y^2 + \frac{1}{2m}p_z^2 \end{aligned}$$

#### Quantum effects:

$$\epsilon = \epsilon_{\text{pot}} + \epsilon_{\text{rot}} + \epsilon_{\text{vib}}$$

#### Average energy of a particle in any system:

$$\bar{\epsilon} = u_0 + \frac{1}{2}v kT$$

### 13.5 Interactions between systems

#### 13.5.1 Work - the mechanical interaction

##### Change in internal energy

$$\Delta E = \Delta Q - \Delta W \quad (\text{thermal and mechanical interactions})$$

### 13.5.2 Particle transfer

##### Chemical potential

$$\Delta E = \Delta Q = \mu \Delta N$$

where  $\mu$  is the chemical potential, and  $N$  is the number of particles transferring

### 13.5.3 First law of thermodynamics

$$dE = dQ - dW + \mu dN$$

### 13.6 Internal energy and the number of accessible states

##### Probability of being in any 1 state

$$P_{\text{any one state}} = 1/\Omega$$

##### Number of states available for $N$ particles:

$$\Omega = \omega \times \omega \times \omega \times \dots = \omega^N$$

##### Number of states available for $N$ indistinguishable particles:

$$\Omega = \frac{\omega^N}{N!} \approx \left(\frac{e\omega}{N}\right)^N$$

##### Corrected number of states available for particles:

$$\omega_c = \omega \quad (\text{distinguishable particles})$$

$$\omega_c = \frac{e\omega}{N} \quad (\text{indistinguishable particles})$$

##### States available to each independent particle

$$\omega_c = C \left(\frac{V}{N}\right) \left(\frac{\frac{1}{2}kT}{N}\right)^{N/2} \quad (\text{gas})$$

$$\omega_c = C \left(\frac{\frac{1}{2}kT}{N}\right)^{N/2} \quad (\text{solid})$$

##### Density of states

$$g(E) \approx C \left(\frac{V}{N}\right)^N \left(\frac{\frac{1}{2}kT}{N}\right)^{Nv/2} \quad (\text{gas})$$

$$g(E) \approx C \left(\frac{\frac{1}{2}kT}{N}\right)^{Nv/2} \quad (\text{solid})$$

### 13.7 Entropy and the second law

##### Number of states for combined system

$$\Omega_0 = \Omega_1 \Omega_2$$

##### Second law of thermodynamics

$$\Delta \Omega_0 > 0$$

##### Entropy

$$S = k \ln \Omega$$

## 13.8 Entropy and thermal interactions

Temperature:

$$\frac{1}{T} = \left( \frac{\partial S}{\partial E} \right)_{V,N}$$

where  $S$  is entropy,  $E$  is internal energy,  $V$  is volume, and  $N$  is the number of particles

First law rewritten:

$$dE = TdS - pdV + \mu dN$$

$$dS = \frac{1}{T}dE + \frac{p}{T}dV - \frac{\mu}{T}dN \quad \left( = \frac{1}{T}dQ \right)$$

Intrinsic/Extrinsic properties

intrinsic:	$T = T_1 = T_2, \quad p = p_1 = p_2$
extrinsic:	$S = S_1 + S_2, \quad V = V_1 + V_2$

Definitions in terms of entropy change

$$\frac{1}{T} = \left( \frac{\partial S}{\partial E} \right)_{V,N} \quad \frac{p}{T} = \left( \frac{\partial S}{\partial V} \right)_{E,N} \quad \frac{\mu}{T} = \left( \frac{\partial S}{\partial N} \right)_{E,V}$$

Energy per degree of freedom:

$$E_{\text{therm}} = \frac{1}{2}N\nu kT$$

Change in states from entropy:

$$\frac{\Omega_f}{\Omega_i} = e^{\Delta S/k}$$

$$= e^{(\Delta E + p\Delta V - \mu\Delta N)/kT}$$

Entropy at finite temperatures:

$$S(T, y) = \int_0^T \frac{C_y dT'}{T'}$$

Heat capacities:

$$C_y \rightarrow 0 \quad T \rightarrow 0$$

## 13.9 Constraints

Thermodynamic potentials

Helmholtz free energy	$F \equiv E - TS;$
Enthalpy,	$H = TS + \mu N;$
Gibbs free energy	$G \equiv E - TS + pV$

Thermodynamic potentials

$$dE = TdS - pdV + \mu dN$$

$$dF = -SdT - pdV + \mu dN$$

$$dH = TdSVdp + \mu dN$$

$$dG = -SdT + Vdp + \mu dN$$

## 13.10 Models

13.10.1 Equations of state

Ideal gases

$$E = \frac{1}{2}N\nu kT$$

$$pV = NkT$$

$$N\mu = NkT \left( \frac{\nu + 2}{2} - \ln \omega_c \right)$$

$$= E + pV - NkT \ln \omega_c$$

Solids

$$E = Nu_0 + \frac{1}{2}N\nu kT$$

$$p = -N \left( \frac{\partial u_0}{\partial V} \right)_{E,N}$$

$$N\mu = Nu_0 + NkT \left( \frac{1}{2}\nu - \ln \omega_c \right)$$

$$= E - NkT \ln \omega_c$$

Van der Waals

$$\left( p + \frac{a}{v^2} \right) (v - b) = RT$$

Differential equations of state

$$dv = -\frac{v}{p}dp + \frac{R}{p}dT \quad \text{ideal gas}$$

$$dv = -\frac{A}{B} \frac{v}{p} dp + \frac{1}{B} \frac{R}{p} dt \quad \text{van der Waals gas}$$

$$\text{with } A = \left( 1 - \frac{b}{v} \right), \quad B = \left( 1 - \frac{a}{pv^2} + \frac{2ab}{pv^3} \right)$$

Molar Heat capacities

$$C_p = \frac{1}{n} \left( \frac{\partial Q}{\partial T} \right)_p, \quad C_V = \frac{1}{n} \left( \frac{\partial Q}{\partial T} \right)_V$$

Isothermal compressibility

$$\kappa = \frac{1}{V} \left( \frac{\partial V}{\partial p} \right)_T$$

$$= \frac{1}{p} \quad \text{ideal gas}$$

$$= \frac{A}{B} \frac{1}{p} \quad \text{van der Waals gas}$$

Coefficient of volume expansion

$$\beta = \frac{1}{V} \left( \frac{\partial V}{\partial T} \right)_p$$

$$= \frac{1}{T} \quad \text{ideal gas}$$

$$= \frac{1}{B} \frac{R}{pv} \quad \text{van der Waals gas}$$

Difference of heat capacities

$$C_p - C_V \approx pv\beta$$

$$= R \quad \text{ideal gas}$$

$$= \frac{1}{B} R \quad \text{van der Waals gas}$$

## Change in internal energy

$$\Delta E = (C_p - pV\beta) \Delta T + (p\kappa - T\beta) V \Delta p$$

## Change in entropy

$$\begin{aligned}\Delta S &= \frac{C_V \kappa}{\beta T} \Delta p + \frac{C_p}{T V \beta} \Delta V \\ &= \frac{C_p}{T} \Delta T - V \beta \Delta p\end{aligned}$$

## 13.11 Special processes

### Isobaric

$$dE = (C_p - pV\beta) dT$$

### Isothermal

$$dE = \left( \frac{T\beta}{\kappa} - p \right) dV$$

### Adiabatic

$$dE = -pdV$$

$$pdV + Vdp = NkdT$$

$$dE = \frac{1}{2} N v \kappa dT$$

$$C_V = \frac{v}{2} R$$

$$C_p = C_V + R$$

$$\beta = 1/T$$

$$\kappa = 1/p$$

### Adiabatic ideal gas

$$TV^{\gamma-1} = \text{constant}$$

$$Tp^{\gamma/(\gamma-1)} = \text{constant}$$

$$pV^\gamma = \text{constant}$$

### 13.11.1 Nonequilibrium processes

#### Throttling

$$\Delta T = \frac{(T\beta - 1)V}{C_p} \Delta p$$

#### Free expansion

$$\Delta T = \left( \frac{p\kappa - T\beta}{\kappa C_V} \right) \Delta V$$

## 13.12 Engines

### Efficiency

$$e = \frac{Q_h - Q_c}{Q_h}$$

### Work done or heat added

$$H_2 - H_1 = Q_{\text{ext}} - W_{\text{ext}} \quad \text{any fluid}$$

$$H_2 - H_1 = nC_p(T_2 - T_1) = Q_{\text{ext}} - W_{\text{ext}}$$

### Carnot efficiency

$$e_{\text{carnot}} = 1 - \frac{T_c}{T_h}$$

## 13.13 Diffusive interactions

### Gibbs free energy

$$\Delta G = \sum_i \mu_i \Delta N_i = 0 \quad \text{at equilibrium}$$

## 13.14 Classical statistics

### Probability system is in state s

$$P_s = C \exp \left( -\frac{\Delta E + p\Delta V - \mu\Delta N}{kT} \right)$$

### Excitation temperature

$$T_e = \frac{\epsilon_1 - \epsilon_0}{k}$$

### RMS speed

$$v_{\text{rms}} = \sqrt{\frac{3kT}{m}}$$

## 13.15 Kinetic Theory

### Velocity distribution

$$P(\mathbf{v}) d^3 v = \left( \frac{\beta m}{2\pi} \right)^{3/2} e^{-\beta mv^2/2} v^2 d^3 v$$

$$P(v) dv = 4\pi \left( \frac{\beta m}{2\pi} \right)^{3/2} e^{-\beta mv^2/2} v^2 dv$$

### Particle flux

$$J = \rho \sqrt{\frac{kT}{2\pi m}}$$

### Collision frequency

$$v_c = \sqrt{2} \rho \sigma \bar{v}$$

where  $\sigma = 4\pi R^2$  and  $R$  is the effective molecular radius  
Mean free path

$$v_c = \sqrt{2} \rho \sigma \bar{v}$$

### Average relative speed of colliding particles

$$\bar{u} = \sqrt{2} \bar{v}$$

### Diffusion constant

$$D = \frac{n \bar{l} \bar{v}}{6}$$

### Thermal conductivity

$$K = \frac{n \bar{l} \bar{v}}{6} \rho \frac{nu}{2} k$$

### Coefficient of viscosity

$$\eta = \frac{n \bar{l} \bar{v}}{6} \rho m$$

# 14 Numerical Analysis

## 14.1 Second Order PDEs classification

### 14.1.1 General Form

$$\begin{aligned} A \frac{\partial^2 \phi}{\partial x^2} + B \frac{\partial^2 \phi}{\partial x \partial y} + C \frac{\partial^2 \phi}{\partial y^2} + D \frac{\partial \phi}{\partial x} + E \frac{\partial \phi}{\partial y} + f\phi + G = 0 \\ A \frac{\partial^2 \phi}{\partial x^2} + B \frac{\partial^2 \phi}{\partial x \partial y} + C \frac{\partial^2 \phi}{\partial y^2} = H \\ H = - \left( D \frac{\partial \phi}{\partial x} + E \frac{\partial \phi}{\partial y} + f\phi + G \right) \end{aligned}$$

### 14.1.2 Characteristics in physical space

$$\left( \frac{dy}{dx} \right)_{\alpha, \beta} = \frac{B \pm \sqrt{B^2 - 4AC}}{2A}$$

### 14.1.3 Equation characteristics

$$\begin{array}{ll} \text{elliptic if} & B^2 - 4AC < 0 \\ \text{parabolic if} & B^2 - 4AC = 0 \\ \text{hyperbolic if} & B^2 - 4AC > 0 \end{array}$$

## 14.2 Finite Difference Schemes

### 14.2.1 First derivative

$$\begin{aligned} u'_i &= \frac{1}{\Delta x} (-u_{i-1} + u_i) + \frac{1}{2} \Delta x u''_i \\ &= \frac{1}{\Delta x} (-u_i + u_{i+1}) - \frac{1}{2} \Delta x u''_i \\ &= \frac{1}{\Delta x} (-u_{i-1} + u_{i+1}) - \frac{1}{6} \Delta x^2 u^{(3)}_i \\ &= \frac{1}{\Delta x} \left( \frac{1}{2} u_{i-2} - 2u_{i-1} + \frac{3}{2} u_i \right) + \frac{1}{3} \Delta x^2 u^{(3)}_i \\ &= \frac{1}{\Delta x} \left( -\frac{3}{2} u_i + 2u_{i+1} - \frac{1}{2} u_{i+2} \right) + \frac{1}{3} \Delta x^2 u^{(3)}_i \end{aligned}$$

## 14.3 Stability Analysis

### 14.3.1 Discrete Perturbation Stability analysis

Consider the parabolic model equation

$$\frac{\partial u}{\partial t} = \alpha \frac{\partial^2 u}{\partial x^2}.$$

Using a first order time and second order spatial derivative, this equation may be written as:

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = \alpha \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{(\Delta x)^2}.$$

If a disturbance  $\epsilon$  at node  $i$  and time level  $n$  is introduced and we search for solution at time level  $n+1$  for all  $i$  nodes, the finite difference eq. becomes:

$$\frac{u_i^{n+1} - (u_i^n + \epsilon)}{\Delta t} = \alpha \frac{u_{i+1}^n - 2(u_i^n + \epsilon) + u_{i-1}^n}{(\Delta x)^2}.$$

If  $u^n = 0$  for all  $i$  the equation reduces to:

$$\frac{u_i^{n+1} - \epsilon}{\Delta t} = \alpha \frac{-2\epsilon}{(\Delta x)^2}$$

or equivalently

$$\begin{aligned} u_i^{n+1} &= \epsilon \left\{ 1 + 2\alpha \left[ \frac{\Delta t}{(\Delta x)^2} \right] \right\} \\ &= \epsilon (1 - 2d) \\ \rightarrow \frac{u_i^{n+1}}{\epsilon} &= (1 - 2d) \end{aligned}$$

where  $d = \alpha \Delta t / (\Delta x)^2$  is known as the *diffusion number*. It's required that,

$$\left| \frac{u_i^{n+1}}{\epsilon} \right| \leq 1$$

or

$$1 - 2d \leq 1 \quad \text{and} \quad 1 - 2d \geq -1$$

### 14.3.2 Von Neumann Stability Analysis

Solution of finite difference equation is expanded in a Fourier series. The decay or growth of the *amplification factor* determines the stability.

Assume a Fourier component for  $u_i^n$  as

$$u_i^n = U^n e^{IP(\Delta x)i}$$

where  $I = \sqrt{-1}$ ,  $U^n$  is the amplitude at time  $n$ , and  $P$  is the wave number in the  $x$ -direction, i.e.,  $\lambda_x = 2\pi/P$ , where  $\lambda_x$  is the wavelength. Similarly,

$$u_i^{n+1} = U^{n+1} e^{IP(\Delta x)i} \quad \text{and} \quad u_{i\pm 1}^n = U^n e^{IP(\Delta x)(i\pm 1)}$$

If phase angle  $\theta = P\Delta x$  is defined, then

$$\begin{aligned} u_i^n &= U^n e^{I\theta i} \\ u_i^{n+1} &= U^{n+1} e^{I\theta i} \\ u_{i\pm 1}^n &= U^n e^{I\theta(i\pm 1)} \end{aligned}$$

Consider again

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = \alpha \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{(\Delta x)^2}$$

or in terms of the diffusion number

$$u_i^{(n+1)} = u_i^n + d(u_{i+1}^n - 2u_i^n + u_{i-1}^n)$$

Substituting the Fourier component and cancelling out terms of  $e^{I\theta i}$ , we get

$$U^{n+1} = U^n [1 + d(e^{I\theta} - e^{-I\theta} - 2)]$$

Using the relation  $\cos \theta = (e^{I\theta} + e^{-I\theta})/2$ , we get

$$U^{n+1} = U^n [1 + 2d(\cos \theta - 1)]$$

Introducing the amplification factor  $U^{n+1} = GU^n$ , we get

$$G = 1 - 2d(1 - \cos \theta).$$

Stability requires,

$$|G| \leq 1 \quad \text{and} \quad |1 - 2d(1 - \cos \theta)| \leq 1$$

so that

$$1 - 2d(1 - \cos \theta) \leq 1$$

and

$$1 - 2d(1 - \cos \theta) \geq -1$$

must be valid for all values of  $\theta$ . With a maximum value of  $(1 - \cos \theta) = 2$ , the LHS becomes  $1 - 4d$ . Solving the new equation gives us a final condition

$$d \leq \frac{1}{2} \quad (3)$$

#### 14.3.3 Scheme Requirements

- *Consistency:* A finite difference approximation of a PDE is consistent if the finite difference equation approaches the PDE as the grid size approaches zero.
- *Stability:* A numerical scheme is said to be stable if any error introduced in the finite difference equation does not grow with the solution of the finite difference equation.
- *Convergence:* A finite difference scheme is convergent if the solution of the finite difference scheme approaches that of the PDE as the grid size approaches zero.

- *Lax's equivalence theorem:* For a FDE which approximates a well-posed, linear initial value problem, the necessary and sufficient condition for convergence is that the FDE must be stable and consistent.

- *The conservative (divergent) form of a PDE:* In this formulation of a physical law, the coefficients of the derivatives are either constant or, if variable, their derivatives do not appear anywhere in the equation.

- *Conservative property of a FDE:* If the finite difference approximation of a PDE maintains the integral property of the conservation law over an arbitrary region containing any number of grid points, it is said to possess a conservative property.

#### 14.4 Classification of equations

Elliptic:	$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0$
Parabolic:	$\frac{\partial T}{\partial t} = \alpha \frac{\partial^2 T}{\partial x^2}$
Hyperbolic:	$\frac{\partial^2 \phi}{\partial t^2} = a^2 \frac{\partial^2 \phi}{\partial x^2}$

# 15 General Mathematics

## 15.1 Arithmetic and Elementary Algebra

### 15.1.1 Powers and Logarithms:

**Powers and roots:**

For real  $a, b, q$ , and  $p$  where  $a, b > 0$

$$\begin{aligned} a^{-p} &= \frac{1}{a^p}, & a^p a^q &= a^{p+q}, & \frac{a^p}{a^q} &= a^{p-q}, \\ (ab)^p &= a^p b^p, & \left(\frac{a}{b}\right)^q &= \frac{a^q}{b^q}, & (a^p)^q &= a^{pq}. \end{aligned}$$

**Logarithms:**

*Definition:*

$$\begin{aligned} \log_a b = c &\longleftrightarrow a^c = b \\ a^{\log_a b} &= b \end{aligned}$$

where  $a > 0, a \neq 1$ , and  $b > 0$ .

*Properties of logarithms:*

$$\begin{aligned} \log_a(bc) &= \log_a b + \log_a c & \log_a\left(\frac{b}{c}\right) &= \log_a b - \log_a c \\ \log_a(b^k) &= k \log_a b & \log_{a^k} b &= \frac{1}{k} \log_a b \quad (k \neq 0) \\ \log_a b &= \frac{a}{\log_b a} \quad (b \neq 1) & \log_a b &= \frac{\log_c b}{\log_c a} \quad (c \neq 1) \end{aligned}$$

### 15.1.2 Binomial Theorem and Related Formulas

*Binomial coefficients:*

$$C_n^k = \binom{n}{k} = \frac{n!}{k!(n-k)!}$$

*Binomial theorem:*

$$(a+b)^n = \binom{n}{k} = \sum_{k=0}^n C_n^k a^{n-k} b^k$$

## 15.2 Elementary Functions

**Exponential function  $e$ :**

$$e \equiv \lim_{n \rightarrow \infty} \left(1 + \frac{1}{n}\right)^n \quad a^x = e^{x \ln a}$$

### 15.2.1 Trigonometric Functions

**Definition of trigonometric functions:**

$$\begin{aligned} \tan \alpha &= \frac{\sin \alpha}{\cos \alpha}, & \cot \alpha &= \frac{\cos \alpha}{\sin \alpha}, \\ \sec \alpha &= \frac{1}{\cos \alpha}, & \csc \alpha &= \frac{1}{\sin \alpha} \end{aligned}$$

### Properties of Trigonometric Functions

*Simplest relations*

$$\begin{aligned} \sin^2 x + \cos^2 x &= 1, & \tan x \cot x &= 1, \\ \sin(-x) &= -\sin x, & \cos(-x) &= \cos x, \\ \tan x &= \frac{\sin x}{\cos x}, & \cot x &= \frac{\cos x}{\sin x}, \\ \tan(-x) &= -\tan x, & \cot(x) &= -\cot x \\ 1 + \tan^2 x &= \frac{1}{\cos^2 x}, & 1 &= \cot^2 x = \frac{1}{\sin^2 x}. \end{aligned}$$

*Reduction formulas*

$$\begin{aligned} \sin(x \pm 2n\pi) &= \sin x & \cos(x \pm 2n\pi) &= \cos x \\ \sin(x \pm n\pi) &= \pm (-1)^n \sin x & \cos(x \pm n\pi) &= \mp (-1)^n \cos x \\ \sin\left(x + \frac{2n+1}{2}\pi\right) &= \pm (-1)^n \cos x & \cos\left(x \pm \frac{2n+1}{2}\pi\right) &= \mp (-1)^n \sin x \\ \sin\left(x \pm \frac{\pi}{4}\right) &= \frac{\sqrt{2}}{2} (\sin x \pm \cos x) & \cos\left(x \pm \frac{\pi}{4}\right) &= \frac{\sqrt{2}}{2} (\cos x \mp \sin x) \\ \tan(x \pm n\pi) &= \tan x & \cot(x \pm n\pi) &= \cot x \\ \tan\left(x \pm \frac{2n+1}{2}\pi\right) &= -\cot x & \cot\left(x \pm \frac{2n+1}{2}\pi\right) &= -\tan x \\ \tan\left(x \pm \frac{\pi}{4}\right) &= \frac{\tan x \pm 1}{1 \mp \tan x} & \cot\left(\pm \frac{\pi}{4}\right) &= \frac{\cot x \mp 1}{1 \pm \cot x} \end{aligned}$$

*Relations between trigonometric functions of a single argument*

$$\begin{aligned} \sin x &= \pm \sqrt{1 - \cos^2 x} = \pm \frac{\tan x}{\sqrt{1 + \tan^2 x}} = \pm \frac{1}{\sqrt{1 + \cot^2 x}} \\ \cos x &= \pm \sqrt{1 - \sin^2 x} = \pm \frac{1}{\sqrt{1 + \tan^2 x}} = \pm \frac{\cot x}{\sqrt{1 + \cot^2 x}} \\ \tan x &= \pm \frac{\sin x}{\sqrt{1 - \sin^2 x}} = \pm \frac{\sqrt{1 - \cos^2 x}}{\cos x} = \frac{1}{\cot x} \\ \cot x &= \pm \frac{\sqrt{1 - \sin^2 x}}{\sin x} = \pm \frac{\cos x}{\sqrt{1 - \cos^2 x}} = \frac{1}{\tan x} \end{aligned}$$

*Addition and subtraction of trigonometric functions*

$$\begin{aligned} \sin x + \sin y &= 2 \sin\left(\frac{x+y}{2}\right) \cos\left(\frac{x-y}{2}\right) \\ \sin x - \sin y &= 2 \sin\left(\frac{x-y}{2}\right) \cos\left(\frac{x+y}{2}\right) \\ \cos x + \cos y &= 2 \cos\left(\frac{x+y}{2}\right) \cos\left(\frac{x-y}{2}\right) \\ \cos x - \cos y &= -2 \sin\left(\frac{x+y}{2}\right) \sin\left(\frac{x-y}{2}\right) \\ \sin^2 x - \sin^2 y &= \cos^2 y - \cos^2 x = \sin(x+y) \sin(x-y) \\ \sin^2 x - \cos^2 y &= \cos^2 y - \cos^2 x = \sin(x+y) \sin(x-y) \\ \tan x \pm \tan y &= \frac{\sin(x \pm y)}{\cos x \cos y} & \cot x \pm \cot y &= \frac{\sin(y \pm x)}{\sin x \sin y} \\ a \cos x - b \sin x &= r \sin(x + \phi) = r \cos(x - \psi) \end{aligned}$$

Here,  $r = \sqrt{a^2 + b^2}$ ,  $\sin \phi = a/r$ ,  $\cos \phi = b/r$ ,  $\sin \psi = b/r$ , and  $\cos \psi = a/r$ .

$$\begin{aligned}\sin x \sin y &= \frac{1}{2} [\cos(x-y) - \cos(x+y)] \\ \cos x \cos y &= \frac{1}{2} [\cos(x-y) + \cos(x+y)] \\ \sin x \cos y &= \frac{1}{2} [\sin(x-y) + \sin(x+y)]\end{aligned}$$

### Powers of trigonometric functions

$$\begin{aligned}\cos^2 x &= \frac{1}{2} \cos 2x + \frac{1}{2} \\ \cos^3 x &= \frac{1}{4} \cos 3x + \frac{3}{4} \cos x \\ \cos^4 x &= \frac{1}{8} \cos 4x + \frac{1}{2} \cos 2x + \frac{3}{8} \\ \cos^5 x &= \frac{1}{16} \cos 5x + \frac{5}{16} \cos 3x + \frac{5}{8} \cos x \\ \sin^2 x &= -\frac{1}{2} \cos 2x + \frac{1}{2} \\ \sin^3 x &= -\frac{1}{4} \sin 3x + \frac{3}{4} \sin x \\ \sin^4 x &= \frac{1}{8} \cos 4x - \frac{1}{2} \cos 2x + \frac{3}{8} \\ \sin^5 x &= \frac{1}{16} \sin 5x - \frac{5}{16} \sin 3x + \frac{5}{8} \sin x \\ \cos^{2n} x &= \frac{1}{2^{2n-1}} \sum_{k=0}^{n-1} C_{2n}^k \cos [2(n-k)x] + \frac{1}{2^{2n}} C_{2n}^n \\ \cos^{2n+1} x &= \frac{1}{2^{2n}} \sum_{k=0}^n C_{2n+1}^k \cos [(2n-2k+1)x] \\ \sin^{2n} x &= \frac{1}{2n-1} \sum_{k=0}^{n-1} (-1)^{n-k} C_{2n}^k \cos [2(n-k)x] + \frac{1}{2^{2n}} C_{2n}^n \\ \sin^{2n+1} x &= \frac{1}{2^{2n}} \sum_{k=0}^n (-1)^{n-k} C_{2n+1}^k \sin [(2n-2k+1)x]\end{aligned}$$

Here,  $n = 1, 2, \dots$  and  $C_m^k = \frac{m!}{k!(m-k)!}$  are the binomial coefficients ( $0! = 1$ ).

### Addition formulas

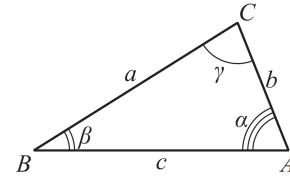
$$\begin{aligned}\sin(x \pm y) &= \sin x \cos y \pm \cos x \sin y \\ \cos(x \pm y) &= \cos x \cos y \mp \sin x \sin y \\ \tan(x \pm y) &= \frac{\tan x \pm \tan y}{1 \mp \tan x \tan y} \\ \cot(x \pm y) &= \frac{1 \pm \tan x \tan y}{\tan x \pm \tan y}\end{aligned}$$

$$\begin{aligned}\cos 2x &= 2 \cos^2 x - 1 = 1 - 2 \sin^2 x \\ \cos 3x &= -3 \cos x + 4 \cos^3 x \\ \cos 4x &= 1 - 8 \cos^2 x + 8 \cos^4 x \\ \cos 5x &= 5 \cos x - 2 \cos^2 x + 16 \cos^4 x \\ \sin 2x &= 2 \sin x \cos x \\ \sin 3x &= 3 \sin x - 4 \sin^3 x \\ \sin 4x &= 4 \cos x (\sin x - 2 \sin^3 x) \\ \sin 5x &= 5 \sin x = 5 \sin x - 20 \sin^3 x + 16 \sin^5 x \\ \tan 2x &= \frac{2 \tan x}{1 - \tan^2 x} \\ \tan 3x &= \frac{3 \tan x - \tan^3 x}{1 - 3 \tan^2 x} \\ \tan 4x &= \frac{4 \tan x - 4 \tan^3 x}{1 - 6 \tan^2 x + \tan^4 x}\end{aligned}$$

## 15.3 Elementary Geometry

### 15.3.1 Plane Geometry

#### Triangles



Plane triangle relations:

$$\alpha + \beta + \gamma = 180^\circ \quad (\text{Sum of angles of a triangle})$$

$$\frac{a}{\sin \alpha} = \frac{b}{\sin \beta} = \frac{c}{\sin \gamma} = 2R \quad (\text{Law of sines})$$

$$c^2 = a^2 + b^2 - 2ab \cos \gamma \quad (\text{Law of cosines})$$

$$\frac{a+b}{a-b} = \frac{\tan\left[\frac{1}{2}(\alpha+\beta)\right]}{\tan\left[\frac{1}{2}(\alpha-\beta)\right]} = \frac{\cot\left(\frac{1}{2}\gamma\right)}{\tan\left[\frac{1}{2}(\alpha-\beta)\right]} \quad (\text{Law of tangents})$$

$$c = a \cos \beta + b \cos \alpha \quad (\text{Theorem on projections})$$

$$p = \frac{1}{2}(a+b+c) \quad (\text{Semi-perimeter})$$

$$\sin \frac{\gamma}{2} = \sqrt{\frac{(p-a)(p-b)}{ab}} \quad (\text{Trigonometric angle formulas})$$

$$\cos \frac{\gamma}{2} = \sqrt{\frac{p(p-c)}{ab}}$$

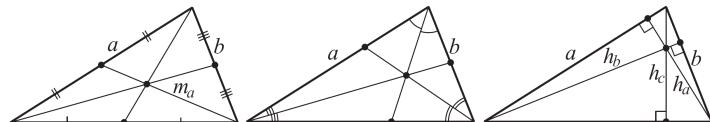
$$\tan \frac{\gamma}{2} = \sqrt{\frac{p(p-c)}{p(p-c)}}$$

$$\sin \gamma = \frac{2}{ab} \sqrt{p(p-a)(p-b)(p-c)}$$

$$\tan \gamma = \frac{c \sin \alpha}{b - c \cos \alpha} = \frac{c \sin \beta}{a - c \cos \beta} \quad (\text{Law of tangents})$$

$$\frac{a+b}{c} = \frac{\cos\left[\frac{1}{2}(\alpha-\beta)\right]}{\sin\left(\frac{1}{2}\gamma\right)} = \frac{\cos\left[\frac{1}{2}(\alpha-\beta)\right]}{\cos\left[\frac{1}{2}(\alpha+\beta)\right]} \quad (\text{Mollweide's})$$

$$\frac{a-b}{c} = \frac{\sin\left[\frac{1}{2}(\alpha-\beta)\right]}{\cos\left(\frac{1}{2}\gamma\right)} = \frac{\sin\left[\frac{1}{2}(\alpha-\beta)\right]}{\sin\left[\frac{1}{2}(\alpha+\beta)\right]}$$



Medians, angle bisectors, and altitudes of triangle

$$m_a = \frac{1}{2} \sqrt{2(b^2 + c^2) - a^2} = \frac{1}{2} \sqrt{a^2 + 4b^2 - 4ab \cos \gamma} \quad (\text{Median})$$

$$l_a = \frac{\sqrt{bc[(b+c)^2 - a^2]}}{b+c} = \frac{\sqrt{4p(p-a)bc}}{b+c} \quad (\text{Angle bisector})$$

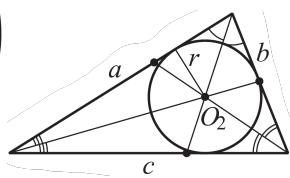
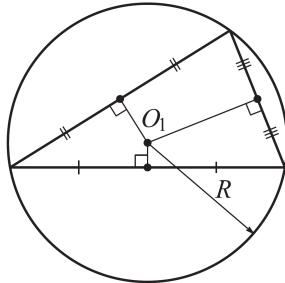
$$= \frac{2cb \cos\left(\frac{1}{2}\alpha\right)}{b+c} = 2R \frac{\sin \beta \sin \gamma}{\cos\left[\frac{1}{2}(\beta-\gamma)\right]}$$

$$= 2p \frac{\sin\left(\frac{1}{2}\beta\right) \sin\left(\frac{1}{2}\gamma\right)}{\sin \beta + \sin \gamma}$$

$$h_a = b \sin \gamma = c \sin \beta = \frac{bc}{2R} \quad (\text{Altitude})$$

$$= 2(p-a) \cos \frac{\alpha}{2} \cos \frac{\beta}{2} \cos \frac{\gamma}{2}$$

$$= 2(p-b) \sin \frac{\alpha}{2} \sin \frac{\beta}{2} \cos \frac{\gamma}{2}$$

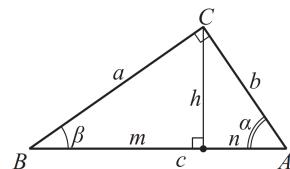


Circumcircle and incircle

$$\begin{aligned} r &= \sqrt{\frac{(p-a)(p-b)(p-c)}{p}} \\ &= p \tan \frac{\alpha}{2} \tan \frac{\beta}{2} \tan \frac{\gamma}{2} = (p-c) \tan \frac{\gamma}{2} \\ R &= \frac{a}{2 \sin \alpha} = \frac{b}{2 \sin \beta} = \frac{c}{2 \sin \gamma} \\ &= \frac{p}{4 \cos\left(\frac{1}{2}\alpha\right) \cos\left(\frac{1}{2}\beta\right) \cos\left(\frac{1}{2}\gamma\right)} \\ d &= \sqrt{R^2 - 2Rr} \end{aligned}$$

Area of a triangle, \$S\$

$$\begin{aligned} S &= \frac{a}{h_a} = \frac{1}{2}ab \sin \gamma = rp \\ &= \sqrt{p(p-a)(p-b)(p-c)} \\ &= \frac{abc}{4R} = 2R^2 \sin \alpha \sin \beta \sin \gamma \\ &= c^2 \frac{\sin \alpha \sin \beta}{2 \sin \gamma} = c^2 \frac{\sin \alpha \sin \beta}{2 \sin(\alpha + \beta)} \end{aligned}$$



Right (right-angled) triangles.

$$\alpha + \beta = 90^\circ$$

$$\sin \alpha = \cos \beta = \frac{a}{c}$$

$$\tan \alpha = \cot \beta = \frac{a}{b}$$

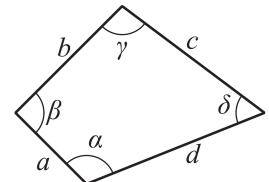
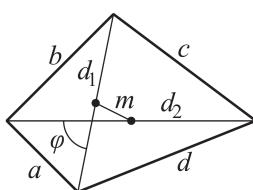
$$a^2 + b^2 = c^2$$

$$h^2 = mn, \quad a^2 = mc \quad b^2 = nc$$

$$\sin \beta = \cos \alpha = \frac{b}{c}$$

$$\tan \beta = \cot \alpha = \frac{b}{a}$$

Polygons



## Areas of quadrilaterals

$$\begin{aligned} p &= \frac{1}{2}(a + b + c + d) \\ S &= \frac{1}{2}d_1d_2 \sin \phi \\ &= \sqrt{p(p-a)(p-b)(p-c)(p-d) - abcd \cos^2\left(\frac{\beta+\delta}{2}\right)} \end{aligned}$$

## 15.4 Algebra

### 15.4.1 Polynomials and Algebraic Equations

#### Linear and Quadratic Equations

*Linear equations*

$$ax + b = 0$$

$$x = -\frac{b}{a}$$

*Quadratic equations*

$$ax^2 + bx + c = 0 \quad (4)$$

$$x_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \quad (5)$$

#### Cubic Equations

*Incomplete cubic equation*

$$y^3 + py + q = 0$$

$$\begin{aligned} y_1 &= A + B, & y_{2,3} &= -\frac{1}{2}(A + B) \pm i\frac{\sqrt{3}}{2}(A - B) \\ A &= \left(-\frac{q}{2} + \sqrt{D}\right)^{1/3}, & B &= \left(-\frac{q}{2} - \sqrt{D}\right)^{1/3} \\ D &= \left(\frac{p}{3}\right)^3 + \left(\frac{q}{2}\right)^2, & i^2 &= -1 \end{aligned}$$

#### Complete cubic equation

$$\begin{aligned} ax^3 + bx^2 + cx + d &= 0 \\ x_k &= y_k - \frac{b}{3a}, & y_k^3 + py_k + q &= 0, & k &= 1, 2, 3 \\ p &= -\frac{1}{3}\left(\frac{b}{a}\right)^2 + \frac{c}{a}, & q &= \frac{2}{27}\left(\frac{b}{a}\right)^3 - \frac{bc}{3a^2} + \frac{d}{a}. \end{aligned}$$

#### Quartic Equations

$$ax^4 + bx^3 + cx^2 + dx + e = 0 \quad (6)$$

$$x = y - \frac{b}{4a} \quad (7)$$

$$y^4 + py^3 + qy + r = 0 \quad (8)$$

$$z^3 + 2pz^2 + (p^2 - 4r)z - q^2 = 0 \quad (9)$$

$$y_1 = \frac{1}{2}(\sqrt{z_1} + \sqrt{z_2} + \sqrt{z_3}) \quad (10)$$

$$y_2 = \frac{1}{2}(\sqrt{z_1} - \sqrt{z_2} - \sqrt{z_3}) \quad (11)$$

$$y_3 = \frac{1}{2}(-\sqrt{z_1} + \sqrt{z_2} - \sqrt{z_3}) \quad (12)$$

$$y_4 = \frac{1}{2}(-\sqrt{z_1} - \sqrt{z_2} + \sqrt{z_3}) \quad (13)$$

#### Algebraic Equations of Arbitrary Degree and Their Properties

*Bounds for the roots of algebraic equations with real coefficients* All roots of polynomials in absolute value do not exceed

$$N = 1 + \frac{A}{|a_n|} \quad (14)$$

where  $A$  is the largest of the coefficients  $|a_0|, |a_1|, \dots, |a_{n-1}|$

# 16 Useful Identities

## 16.1 Series

### 16.1.1 Expansion of asymptotic series to a power

$$\begin{aligned} (x_0 + \epsilon x_1 + \epsilon^2 x_2 + \epsilon^3 x_3 + \dots)^n &= x_0^n \\ &\quad + \epsilon n x_0^{n-1} x_1 \\ &\quad + \epsilon^2 \left[ \frac{n(n-1)}{2!} x_0^{n-2} x_1^2 + n x_0^{n-1} x_2 \right] \\ &\quad + \epsilon^3 \left[ \frac{n(n-1)(n-2)}{3!} x_0^{n-3} x_1^3 + n(n-1) x_0^{n-2} x_1 x_2 + n x_0^{n-1} x_3 \right] \\ &\quad + \epsilon^4 \left[ \frac{n(n-1)(n-2)(n-3)}{4!} x_0^{n-4} x_1^4 + \frac{n(n-1)(n-2)}{2!} x_0^{n-3} x_1^2 x_2 + \frac{n(n-1)}{2!} x_0^{n-2} (x_2^2 + 2x_1 x_3) + n x_0^{n-1} x_4 \right] \end{aligned}$$

## Important Series Expansions

$$\text{Taylor: } f(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \frac{f'''(a)}{3!}(x-a)^3 + \dots + \frac{f^n(a)}{n!}(x-a)^n + \dots$$

$$(1+x)^\alpha = 1 + ax + \frac{\alpha(\alpha-1)}{2!}x^2 + \frac{\alpha(\alpha-1)(\alpha-2)}{3!}x^3 + \dots$$

$$(1+x)^{-1} = 1 - x + x^2 - x^3 + \dots; \quad -1 < x < 1$$

$$(1+x)^{1/2} = 1 + \frac{x}{2} - \frac{x^2}{8} + \frac{x^3}{16} - \frac{5x^4}{128} + \frac{7x^5}{256} + \dots; \quad -1 < x < 1$$

$$(1+x)^{-1/2} = 1 - \frac{x}{2} + \frac{3}{8}x^2 - \frac{5x^3}{16} + \frac{35x^4}{128} - \frac{63x^5}{256} + \dots; \quad -1 < x < 1$$

$$\ln x = \frac{x-1}{x} + \frac{1}{2}\left(\frac{x-1}{x}\right)^2 + \frac{1}{3}\left(\frac{x-1}{x}\right)^3 + \dots; \quad x \geq \frac{1}{2};$$

$$\ln x = (x-1) - \frac{1}{2}(x-1)^2 + \frac{1}{3}(x-1)^3 - \dots; \quad |x-1| \leq 1, \quad x \neq 0$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots + (-1)^{n+1} \frac{x^n}{n}; \quad |x| \leq 1 \quad x \neq -1$$

$$\frac{1}{1-x} = 1 + x + x^2 + \dots + x^n + \frac{x^n}{1-x}; \quad |x| < 1; \quad \frac{1}{(1-x)^2} = 1 + 2x + 3x^2 + \dots + nx^n + R; \quad |x| < 1; \quad \lim_{n \rightarrow \infty} R_n \rightarrow 0$$

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots + \frac{x^n}{n!} + \dots; \quad \sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots; \quad \cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots$$

$$\tan x = x + \frac{x^3}{3} + \frac{2x^5}{15} + \dots; \quad \cot x = \frac{1}{x} - \frac{x}{3} - \frac{x^3}{45} - \frac{2x^5}{245} + \dots$$

$$\sec x = 1 + \frac{x^2}{2} + \frac{5x^4}{24} + \frac{61x^6}{720} + \dots; \quad \csc x = \frac{1}{x} + \frac{x}{6} + \frac{7}{360}x^3 + \frac{31}{15120}x^5 + \dots$$

$$\sin^{-1} x = x + \frac{x^3}{2 \cdot 3} + \frac{1 \cdot 3 x^5}{2 \cdot 4 \cdot 5} + \frac{1 \cdot 3 \cdot 5 x^7}{2 \cdot 4 \cdot 6 \cdot 7} + \dots; \quad |x| < 1; \quad \tan^{-1} x = x - \frac{x^3}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \dots; \quad |x| \leq 1;$$

$$\tan^{-1} x = \frac{\pi}{2} - \frac{1}{x} + \frac{1}{3x^3} - \frac{1}{5x^5} + \dots; \quad x > 1; \quad \tan^{-1} x = -\frac{\pi}{2} - \frac{1}{x} + \frac{1}{3x^3} - \frac{1}{5x^5} + \dots; \quad x < -1$$

$$\cot^{-1} x = \tan^{-1}(x^{-1}); \quad \sec^{-1} x = \cos^{-1}(x^{-1}); \quad \csc^{-1} x = \sin^{-1}(x^{-1}); \quad -1 \leq x \leq 1;$$

$$\sinh x = x + \frac{x^3}{3!} + \frac{x^5}{5!} + \dots; \quad \cosh x = 1 + \frac{x^2}{2!} + \frac{x^4}{4!} + \dots$$

$$\tanh x = x - \frac{x^3}{3} + \frac{2x^5}{15} - \frac{17x^7}{315} + \dots; \quad |x| < \frac{\pi}{2}; \quad \coth x = \frac{1}{x} + \frac{x}{3} - \frac{x^3}{45} + \frac{2x^5}{945} + \dots$$

$$\operatorname{sech} x = 1 - \frac{x^2}{2} + \frac{5x^4}{24} - \frac{61x^6}{720} + \dots; \quad \operatorname{csch} x = \frac{1}{x} - \frac{x}{6} + \frac{7x^3}{360} - \frac{31x^5}{15120} + \dots$$

$$\begin{aligned} \sinh^{-1} x &= x - \frac{1}{2 \cdot 3}x^3 + \frac{1 \cdot 3}{2 \cdot 4 \cdot 5}x^5 - \frac{1 \cdot 3 \cdot 5}{2 \cdot 4 \cdot 6 \cdot 7}x^7 + \dots; \quad |x| < 1 \\ &= \ln 2x + \frac{1}{2 \cdot 2x^2} - \frac{1 \cdot 3}{2 \cdot 4 \cdot 4x^4} + \frac{1 \cdot 3 \cdot 5}{2 \cdot 4 \cdot 6 \cdot 6x^6} + \dots; \quad |x| > 1 \end{aligned}$$

$$\cosh^{-1} x = \ln 2x - \frac{1}{2 \cdot 2x^2} - \frac{1 \cdot 3}{2 \cdot 4 \cdot 4x^4} - \frac{1 \cdot 3 \cdot 5}{2 \cdot 4 \cdot 6 \cdot 6x^6} + \dots; \quad |x| > 1$$

$$\tanh^{-1} x = x + \frac{x^3}{3} + \frac{x^5}{5} + \frac{x^7}{7} + \dots; \quad |x| < 1; \quad \coth^{-1} x = \frac{1}{x} + \frac{1}{3x^3} + \frac{1}{5x^5} + \frac{1}{7x^7} + \dots; \quad |x| > 1$$

$$\cos^3 x = 1 - \frac{3}{2}x^2 + \frac{7}{8}x^4 - \frac{x^6}{8} + \dots; \quad \sin^3 x = x^3 - \frac{1}{2}x^5 + \frac{3}{4}x^7 - \frac{1}{216}x^9 + \dots$$

## Useful Trigonometric Identities

### FORMULAS FOR ADDITION AND SUBTRACTION

$$\begin{aligned}\sin(a \pm b) &= \sin a \cos b \pm \cos a \sin b ; & \cos(a \pm b) &= \cos a \cos b \mp \sin a \sin b \\ \tan(a \pm b) &= \frac{\tan a \pm \tan b}{1 \mp \tan a \tan b} & \cot(a \pm b) &= \frac{\cot a \cot b \mp 1}{\cot b \pm \cot a} & \tan\left(\frac{\pi}{4} \pm b\right) &= \frac{1 \pm \tan b}{1 \mp \tan b} = \frac{\cos b \pm \sin b}{\cos b \mp \sin b}\end{aligned}$$

### WERNER'S FORMULAS

$$\begin{aligned}\sin a \sin b &= \frac{1}{2}[\cos(a - b) - \cos(a + b)] ; & \sin a \cos b &= \frac{1}{2}[\sin(a + b) + \sin(a - b)] \\ \cos a \cos b &= \frac{1}{2}[\cos(a + b) + \cos(a - b)]\end{aligned}$$

### INVERSE OF WERNER'S FORMULAS

$$\begin{aligned}\sin a + \sin b &= 2 \sin\left(\frac{a+b}{2}\right) \cos\left(\frac{a-b}{2}\right) ; & \sin a - \sin b &= 2 \cos\left(\frac{a+b}{2}\right) \sin\left(\frac{a-b}{2}\right) \\ \cos a + \cos b &= 2 \cos\left(\frac{a+b}{2}\right) \cos\left(\frac{a-b}{2}\right) ; & \cos a - \cos b &= -2 \sin\left(\frac{a+b}{2}\right) \sin\left(\frac{a-b}{2}\right)\end{aligned}$$

### OTHER FORMULAS TRANSFORMING SUMS INTO PRODUCTS OF FUNCTIONS

$$\begin{aligned}\tan a + \tan b &= \sin(a + b) / (\cos a \cos b) ; & \tan a - \tan b &= \sin(a - b) / (\cos a \cos b) \\ \cot a + \cot b &= \sin(a + b) / (\sin a \sin b) ; & \cot a - \cot b &= -\sin(a - b) / (\sin a \sin b)\end{aligned}$$

### DUPLICATION FORMULAS

$$\begin{aligned}\sin 2a &= 2 \sin a \cos a ; & \cos 2a &= 2 \cos^2 a - 1 = 1 - 2 \sin^2 a = \cos^2 a - \sin^2 a \\ \tan 2a &= 2 \tan a / (1 - \tan^2 a) ; & \cot 2a &= (\cot^2 a - 1) / (2 \cot a)\end{aligned}$$

### TRIPPLICATION FORMULAS

$$\begin{aligned}\sin 3a &= 3 \sin a - 4 \sin^3 a ; & \cos 3a &= 4 \cos^3 a - 3 \cos a \\ \tan 3a &= (3 \tan a - \tan^3 a) / (1 - 3 \tan^2 a) ; & \cot 3a &= (\cot^3 a - 3 \cot a) / (3 \cot^2 a - 1)\end{aligned}$$

### BISECTION FORMULAS

$$\begin{aligned}\sin \frac{a}{2} &= \pm \sqrt{\frac{1}{2}(1 - \cos a)} ; & \cos \frac{a}{2} &= \pm \sqrt{\frac{1}{2}(1 + \cos a)} \\ \tan \frac{a}{2} &= \pm \sqrt{\frac{\frac{1}{2}(1-\cos a)}{\frac{1}{2}(1+\cos a)}} ; & \cot \frac{a}{2} &= \pm \sqrt{\frac{\frac{1}{2}(1+\cos a)}{\frac{1}{2}(1-\cos a)}}\end{aligned}$$

### FORMULAS FOR CONVERTING POWERS INTO MULTIPLE ANGLES

$$\begin{aligned}\sin^2 a &= \frac{1}{2}(1 - \cos 2a) ; & \cos^2 a &= \frac{1}{2}(1 + \cos 2a) \\ \sin^3 a &= \frac{1}{4}(3 \sin a - \sin 3a) ; & \cos^3 a &= \frac{1}{4}(3 \cos a + \cos 3a) \\ \sin^4 a &= \frac{1}{8}(\cos 4a - 4 \cos 2a + 3) ; & \cos^4 a &= \frac{1}{8}(\cos 4a + 4 \cos 2a + 3) \\ \sin^5 a &= \frac{1}{16}(10 \sin a - 5 \sin 3a + \sin 5a) ; & \cos^5 a &= \frac{1}{16}(10 \cos a + 5 \cos 3a + \cos 5a) \\ \sin^6 a &= \frac{1}{32}(10 - 15 \cos 2a + 6 \cos 4a - \cos 6a) ; & \cos^6 a &= \frac{1}{32}(10 + 15 \cos 2a + 6 \cos 4a + \cos 6a)\end{aligned}$$